



**OCEANS '09
IEEE Bremen**
11-14 May
Bremen
Germany



Final Program

OCEANS '09 IEEE Bremen

Balancing technology with future needs

May 11th – 14th 2009 in Bremen, Germany



Local Organizing Committee



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Gerold Wefer
Bremen University,
MARUM

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Christoph Waldmann
MARUM

Conference Chair



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University of applied
sciences
Bremerhaven

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Microbiology

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MARUM

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Chair



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Welcome from the General Chair

WELCOME FROM THE GENERAL CHAIR



In the Earth system the ocean plays an important role through its intensive interactions with the atmosphere, cryosphere, lithosphere, and biosphere. Energy and material are continually exchanged at the interfaces between water and air, ice, rocks, and sediments. In addition to the physical and chemical processes, biological processes play a significant role.

Vast areas of the ocean remain unexplored. Investigation of the surface ocean is carried out by satellites. All other observations and measurements have to be carried out in-situ using research vessels and special instruments. Ocean observation requires the use of special technologies such as remotely operated vehicles (ROVs), autonomous underwater vehicles (AUVs), towed camera systems etc. Seismic methods provide the foundation for mapping the bottom topography and sedimentary structures.

We cordially welcome you to the international OCEANS '09 conference and exhibition, to the world's leading conference and exhibition in ocean science, engineering, technology and management. OCEANS conferences have become one of the largest professional meetings and expositions devoted to ocean sciences, technology, policy, engineering and education. They include participants from government, industry, and academia.

OCEANS '09 addresses scientists, engineers and representatives from authorities and companies, who are active in marine research and technological development. The main topics cover new methods and technologies in ocean exploration.

A number of lectures, organised as special topic sessions, will provide an overview of the latest technological and scientific approaches in ocean research, including recent issues on basic research, and utilisation of natural resources. This is supplemented by an international marine technology exhibition, where leading companies present their products and services.

The technical programme will be complemented by a variety of professional tutorials: Expert presentations partly accompanied by practical exercises offer the opportunity to gain deeper insight into specific technologies and applications.

Furthermore, part of the program will address the future generation of scientists and engineers: university students, undergraduates and Ph.D. students.

Welcome

In addition, during one of the OCEANS '09 Workshops a forum will be given to discuss the future impact of climatic changes on mankind.

We are looking forward to meeting you in Bremen and wish you a pleasant stay.



Prof. Gerold Wefer
General Chair
Oceans'09 IEEE Bremen

WELCOME TO BREMEN, GERMANY

Bremen, home of the world famous Bremen Town Musicians, is widely known as the vibrant, multifaceted heart of north-west Germany. The 1200 years old Hanseatic city has an exceptional quality that ensures a unique metropolitan city experience. With its sister city of Bremerhaven Bremen forms the smallest state in the German Federal Republic. Main industries are automotive engineering, aerospace technology, food, port management, marine and offshore business.

Bremen – City of Science

Bremen and Bremerhaven have long been fostering a lively exchange of science and industry. Within the last couple of years the City of Bremen has developed into one of the central locations of marine research and technology in Germany and in Europe.

The major research institutions are the MARUM – Centre for Marine Environmental Sciences, which belongs to the University of Bremen, the Jacobs University of Bremen, the Alfred Wegener Institute for Polar Research (the largest marine research institution in Germany) and the Max Planck Institute for Marine Microbiology, which is spearheading the investigation of micro organisms in the ocean environment. Overall around 1,500 people are now working in the field of marine research in the state of Bremen.

Bremen – City of Marine Industry

Bremen plays a leading role in marine and offshore technology in Germany. Highly specialized shipyards and suppliers of components for offshore industry and for the German Navy form the economic cornerstone for the successful, worldwide maritime branch of local industry.

Useful Addresses & Phone Numbers

USEFUL ADDRESSES AND PHONE NUMBERS

Emergency calls

Police department 110

Fire department/ambulance 112

Cabs

Taxi-Ruf Bremen #49 (0) 421 14014

Taxi Roland - Bremen #49 (0) 421 14433

Bremen Congress and Exhibition Centre CCB

Hollerallee 99

28215 Bremen

Phone #49 (0) 421 3789 0 Fax #49 (0) 421 3789 600

Tourism offices: BTZ Bremer Touristik Zentrale GmbH

Findorffstr 105

28215 Bremen

Phone #49 (0) 421 1805 101030 Fax #49 (0) 421 30800 30

Office downtown: Obernstrasse/Liebfrauenkirchhof

Open: Mon - Fri 10h00 - 18h30

Sat - Sun 10h00 - 16h00

Office at central train station

Open: Mon - Fri 09h00 - 19h00

Sat - Sun 9h30 - 18h00

HOTELS

Park Hotel Bremen

Im Bürgerpark

28209 Bremen

Phone #49 (0) 421 3408 0 Fax #49 (0) 421 3408 602

Swissôtel Bremen

Hillmannplatz 20

28195 Bremen

Phone #49 (0) 421 62000 0 Fax #49 (0) 421 62000 222

Maritim Hotel Bremen

Hollerallee 99

28215 Bremen

Phone #49 (0) 421 3789 0 Fax #49 421 3789 600

Useful Adresses & Phone Numbers

Best Western Wellness Hotel zur Post

Bahnhofsplatz 11

28195 Bremen

Phone #49 (0) 421 3059 0

Fax #49 (0) 421 3059 591

InterCity Hotel

Bahnhofsplatz 17-18

28195 Bremen

Phone #49 (0) 421 1603-100

Fax #49 (0) 421 1603 599

Hotel Mercure Columbus

Bahnhofsplatz 5-7

28195 Bremen

Phone #49 (0) 421 3012 0

Fax #49 (0) 421 3012 123

Hotel Bremer Haus

Lönningstr. 16-20

28195 Bremen

Phone #49 (0) 421 3294 0

Fax #49 (0) 421 3294 411

Best Western Hotel Schaper-Siedenburg

Bahnhofstr. 8

28195 Bremen

Phone #49 (0) 421 3087 0

Fax #49 (0) 421 3087 88

Prizeotel Bremen

Theodor-Heuss-Allee 12

28215 Bremen

Phone #49 (0) 421 2222 100

Fax #49 (0) 421 2222 101

Hotel Ibis Bremen Centrum

Rembertiring 51

28203 Bremen

Phone #49 (0) 421 3697 0

Fax #49 (0) 421 3697 109

Bremen Youth Hostel

Kalkstraße 6

28195 Bremen

Phone #49 (0) 421 163820

Fax #49 (0) 421 1638255

CONFERENCE INFORMATION

SCHEDULE

Registration and Information Desks Hours

The Registration and Information Desks are located in the lobby of the Exhibit Hall (Halle 4, Messe Bremen). They will be open for registration and general inquiries according to the following schedule:

Monday	May 11	08h00 – 17h00
Tuesday	May 12	07h30 – 18h00
Wednesday	May 13	07h30 – 18h00
Thursday	May 14	07h30 – 15h00

Tutorial Hours

Monday, May 11

T6, T8	May 11	09h00 – 13h00
T5, T7, T11, T13	May 11	14h00 – 18h00
T14	May 11	09h00 – 17h00

Exhibit Hall and Student Poster Competition

The Exhibit Hall is hall 4, on the ground floor of Messe Bremen.

The Exhibit Hall will be open and the Student Posters will be on display in the connecting corridor between the Exhibit Hall and the Congress Centre Bremen (CCB) according to the following schedule:

Tuesday	May 12	08h00 – 19h30 10h45 exhibit opening
Wednesday	May 13	08h00 – 18h00
Thursday	May 14	08h00 – 15h00

Coffees

Coffees will be available throughout each Conference Day in the Exhibit Hall complimentary for all attendees during the coffee breaks according to the following schedule:

Conference Information

Tuesday	May 12		15h10 – 15h40
Wednesday	May 13	10h10 – 10h40	15h10 – 15h40
Thursday	May 14	10h10 – 10h40	

There will also be a coffee shop in the Exhibit Hall (drinks on sale) throughout the conference days.

Lunches

Lunches (which are included in the full conference registration fee) are provided on Tuesday and Wednesday. The self-service style lunches are offered in the Exhibit Hall (one lunchbox or one helping per person per voucher).

Hosted by OES and Deutsche See	Tuesday, May 12	12h00 – 13h30
	Wednesday, May 13	12h00 – 13h30

On Thursday, lunch packages will be on purchase around midday in the Exhibit Hall (trolley).

BUSINESS

Conference Hours

The Plenary and Technical Sessions take place in the Congress Centre Bremen (CCB, Hansesaal) which is connected to the Exhibit Hall via a corridor on the first floor.

The sessions are planned according to the following schedule:

Tuesday	May 12	09h00-12h00		Opening and Plenary session
Tuesday	May 12	13h30-17h20		Technical Sessions
Wednesday	May 13	08h30-12h00	13h30-17h20	Technical Sessions
Thursday	May 14	08h30-12h00	13h30-15h10	Technical Sessions

Conference Information

Speaker Centre / Upload Room

The upload area and the speaker ready area are located in the Kaisen Saal.

Note for speakers:

All speakers are required to upload their presentations to the central server prior to their talk. They can do so using an USB memory stick, CDs, DVDs or via Internet download.

Monday	May 11	14h00 – 17h30
Tuesday	May 12	08h00 – 18h00
Wednesday	May 13	08h00 – 18h00
Thursday	May 14	08h00 – 15h00

COMMUNICATIONS

Language

The official language of OCEANS '09 IEEE Bremen is English and all presentations must be given in English. No simultaneous interpretation service will be provided.

Internet Access

Internet access via LAN is located in the Exhibit Hall. You are welcome to use this during the official opening hours of the Exhibition. Wireless internet access is also available (voucher with personal code in your conference bag).

Messages

Messages between delegates may be posted on the message board located in the lobby of the Exhibit Hall.

Mobile Phone

Please ensure that your cellular phone, pager, etc. are turned OFF or put on silent/vibrant mode during sessions.

Conference Information / Social Events

MISCELLANEOUS

Badges

Please wear your name badge at all times. This will ensure your admittance to the technical sessions and the Exhibit Hall.

Tickets for Social Events

You have been issued an envelope containing your name badge, a receipt and the tickets you have ordered for the tours and social events when you checked-in at the Registration Desk. Please bring the appropriate ticket(s) to all social events. Additional tickets will be available for purchase at the Registration Desk, based on space availability.

Additional tickets for the lunches can be purchased directly, after self-service, at the cash-desk in the Exhibit Hall.

SOCIAL EVENTS

The following functions are included with full registrations. Additional tickets can be purchased at the Registration Desk.

Events	Monday May 11	Tuesday May 12	Wednesday May 13
Icebreaker	17h30 Foyer CCB		
Exhibitors' Reception		18h00 Exhibit Hall	
Lunch with OES and Deutsche See			12h00 Exhibit Hall
Lunch		12h00 Exhibit Hall	
Town Hall Reception			18h30 Town Hall Upper Hall
Banquet			19h30 Town Hall Historic Cellar

TOURISM INFORMATION

A tourist information desk will be located in the lobby of the Exhibit Hall to provide information, brochures and reservations for attractions in the Bremen area.

CITY AND AREA TOURS

“Bremen - City of science and aerospace”

The following events and sightseeing tours are offered. In addition places of interest are recommended, which you can visit individually to get to know the City of Bremen and Bremerhaven close-up.

TOURS (to be booked in advance)

1. Guided walk through the historic old city

Sunday, May 10, 16h00 or

Monday, May 11, 10h00

Meeting point: Statue of Roland, market square.

The tour ends in the historical city.

English speaking tour guide

Duration: 1,5 to 2 hours

Price/person: € 9,00

2. Sightseeing tour (by bus)

Bremen - the Free Hanseatic City, explore 1200 years of history

Sorry, cancelled due to poor demand.

3. Walking Dinner

3-course-menu in different restaurants, combined with a short walk through the historic centre. The tour ends at the Restaurant “Bremer Ratskeller”.

Sorry, cancelled due to poor demand.

4. Tour with the night watchman through the Schnoor

English speaking guide (watchman)

Monday, May 11, 21h00 - 22h30

Meeting-point: Roland, market square.
The tour ends in the historical city.
Duration: about 1,5 hours
Price/person: € 12,00

5. Havenwelten Bremerhaven

German Emigration Centre, bark "Seute Deern", German Maritime Museum, Zoo am Meer - the zoo by the sea

Sorry, cancelled due to poor demand.

6. Space Tour - EADS Astrium

How do astronauts live, work and sleep in space? Find out this and other facts on a fascinating guided tour of the Bremenhalle and the ISS module at EADS Astrium.

Sorry, cancelled due to poor demand.

FURTHER PLACES TO VISIT:

Universum Science Centre Bremen

On more than 4000 sqm, science can be 'grasped' in a literal sense through playful, hands-on experience. Three expeditions into Humankind, Planet Earth and the Cosmos.

Schlachte Embankment

A wealth of restaurants with beer gardens. Riverboat, quayside, antique & flea market.

Überseemuseum - Overseas Museum – anthropology, trade and natural history

Around the world in 80 minutes: discover a variety of new worlds with everything from African art, exotic animals and plants, and gold from the Americas. Founded in 1896.

Focke Museum

Bremen Regional Museum for Art and Cultural History.
1,200 years of urban and cultural history in four historical buildings, fascinating examples of applied art – and much more.

Auswandererhaus-German Emigration Center, Bremerhaven
„setting off for a new life...” Europe’s largest emigration museum deals with the emigration of German people to the New World during the 19th and 20th century. Research your own family’s past! Bremerhaven is about 60 km from Bremen city and can be reached individually by car or railway.

Weserburg – Museum of contemporary art
Germany’s first collectors’ museum for international contemporary art and Europe’s largest collection of art publications. Bremen and the avant-garde - yet another tradition.

Kunstsammlungen – art collections - Böttcherstr.
The art collections reside in the Museum in the Roselius House, modelled on a historic Bremer patrician residence of the 16th-century, with works from the Middle Ages to the Baroque, and in the Paula Modersohn-Becker Museum, a significant 20th century expressionist building.

Bremer Geschichtenhaus – Bremen’s house of history
Accompany some of Bremen’s famous names on an entaining journey through the city’s past, which is vividly brought to life.

PLENARY SESSION

Tuesday, May 12, 2009

09h00 - 09h10

Opening remarks by the organisers and the president of the IEEE Oceanic Engineering Society

Jerry C. Carrol

09h10 - 09h25

Welcome by the city of Bremen - Minister for Economic Affairs and Ports of the state of Bremen

Minister Ralf Nagel

Ralf Nagel is Minister for Economic Affairs and Ports of the State of Bremen since June 2007. He graduated in 1985 and started working as a scientific employee for the Member of the Bundestag Gunter Huonker. After different positions in the field of Building and Urban Affairs within the Social Democratic

Party and in public administration he first became Undersecretary for this sector and then Undersecretary for Economy and Technology in the State of Sachsen-Anhalt. He joined the federal government as an Undersecretary for Transport, Building and Urban Affairs in 2000.

09h25 - 09h45

The European contribution to global environmental programs

Director of Directorate I, Environment, of the European Commission, Manuela Soares

Manuela Soares was born in Portugal, where she attended the University of Porto and received an MSc, followed by a PhD, in Chemical Engineering. She then took up a position as an Assistant Professor in the Department of Chemical Engineering within the Faculty of Engineering of the University of Porto. Manuela Soares joined the Research Directorate- General of the European Commission in 1987, where she has held the posts of Scientific Officer, Head of Unit, Adviser and finally Director of the Environment Programme in the Research Directorate- General.

09h45 - 10h05

The impact of underwater acoustic on ocean research and surveillance

François-Régis Martin-Lauzer, Director NURC

Dr. François-Régis MARTIN-LAUZER joined the NURC in November 2006 as Director, the senior manager at NURC. He provides executive, technical, and scientific direction in the performance of NURC's mission of planning, managing and executing naval science and technology research for NATO. Acting as Chief Operating Officer of the NURC from 1 October 2008, he works closely with NURC's Chief Scientist, with the NATO Research and Technology Board and the NATO Naval Armaments group of the Conference of NATO national armaments directors in the identification, prioritization, and support of specific areas of science and technology development.

10h05 - 10h25

The role of ocean technology in marine research

Chair of the German Marine Research Consortium KDM, Prof. Gerold Wefer

Gerold Wefer is currently Director of the Research Centre MARUM at the University of Bremen. He received his diploma and PhD degree in Marine Geosciences from the University of Kiel/ Germany in 1973 and 1976 respectively. After two stays as a visiting researcher at SCRIPPS Institution of Oceanogra-

phy he became Full Professor of Geosciences at the University of Bremen in 1985. As one of the first faculty members of the newly established Department of Geosciences he was one of the driving forces during the establishment of today's well known DFG Research Centre MARUM. He has acted in a number of functions for instance as the speaker for DFG priority programs, the head of the DFG Senate for Oceanography, member of the Consortium German Marine Science Institutions (KDM, since 2007 President), Coordinator "Stadt der Wissenschaft" Bremen/Bremerhaven, Member SASEC, IODP, Member Senate Leibniz Gemeinschaft, Head of Steering Committee Wissenschaft im Dialog, Chairman of the Geo-Commission of the Deutsche Forschungsgemeinschaft and on a number of other committees.

10h25 - 10h45

The strategy of the German government in regard to ocean and maritime technology

Maritime coordinator of the German Federal Government, Undersecretary of economy Dagmar Wöhrl

In November 2005 Dagmar Wöhrl was appointed Undersecretary of economy at the Federal Ministry of Economy and in November 2006 Maritime coordinator of the German Federal Government. She started her political career as a member of the local government of the City of Nuremberg. Since 1994 Ms. Wöhrl is Member of the German Bundestag. Between 2002 and 2005 she has been spokeswoman for economy issues of the Christian Democratic Party.

WORKSHOP ON OCEAN OBSERVATORIES

Thursday, May 14, 2009

13h30 - 14h00

Transforming Ocean, Earth and Life Sciences with Distributed Submarine Sensor Networks Wired to Next-Generation Internet

John R. Delaney, School of Oceanography, University of Washington

14h00 - 15h00

Scientific and technical objectives of current ocean observatory initiatives - Presentations by representatives of OOI, NEPTUNE- Canada, ESONET etc.

15h00 - 16h00

Discussion on global integration aspects and possible road maps

16h00 - 17h00

Get-Together with snacks sponsored by MARIPRO

TUTORIALS

T5 - HIGH-FREQUENCY OVER-THE-HORIZON RADAR APPLICATIONS IN OCEANOGRAPHY **Salon Danzig**

During the last decade, High-Frequency (HF) radar remote sensing of oceanographic parameters became more and more important. These radar systems are able to monitor large areas of the ocean, far behind the horizon. HF radar networks are currently being installed along the East and West Coasts of the US to contribute to the future monitoring systems (NOAA's IOOS program). This tutorial is split into three parts:

A. Basic Physics of HF Radar:

Electromagnetic wave propagation, both ground wave and sky wave, dependency on ionospheric conditions, scattering processes at the ocean surface, algorithms to derive surface current maps, ocean wave spectra, and wind direction.

B. Technical Solutions:

Range resolution by Frequency Modulated Continuous Wave (FMCW) modulation and by pulses, azimuthal resolution by beam forming and by direction finding; advantages and limitations of the different technologies; algorithms to reduce the impact of Radio Frequency Interference (RFI).

C. Application of HF Radar Monitoring Systems:

How to set up a monitoring system by combining fine-scale ocean current models with HF radar measurements by data assimilation as demonstrated within the European project "European Radar Ocean SENSing" (EuroROSE); algorithms required for HF radar networks; application of HF radars for ship detection and tracking.

Presenter's Bio - Klaus-Werner Gurgel

Klaus-Werner Gurgel (IEEE M'94) received the diploma in electrical engineering from the University of Hannover, Hannover, Germany, in 1980 and the Ph.D. in geosciences from the University of Hamburg, in 1993.

From 1980 to 1985, he was responsible for the technical development and deployment of the University of Hamburg's HF radar during numerous experiments, which at that time was based on NOAA's Coastal Ocean Dynamics Applications Radar (CODAR). From 1985 to 1993, he was working on a ship borne version of the CODAR for applications at the Arctic Front. In 1996, he developed a new HF radar system called Wellen RADar (WERA) within the European Union (EU)funded project "Surface Current And Wave Variability Experiment" (SCAWVEX), which was later on used within the EU funded projects "European Radar Ocean SENSing" (EuroROSE) and "Weather Information

Network, Guidance, and Supervision onboard Ships” (Wings-for-Ships). After a technology transfer to industry, WERA is now commercially available and applied by several Universities and Institutions worldwide.

Dr. Gurgel is currently a research scientist at the University of Hamburg, Institute of Oceanography, and involved within numerous projects on radar remote sensing. Since November 2004, he is Adjunct Professor at the Division of Meteorology and Physical Oceanography of the Rosenstiel School of Marine and Atmospheric Science, University of Miami, FL, USA. Dr. Gurgel is a member of IEEE Oceanic Engineering, Geoscience & Remote Sensing, and Antennas and Propagation Society.

T6 - THE STOCHASTIC MATCHED FILTER: APPLICATIONS TO DE-NOISING AND DETECTION

Salon Scharoun

In several domains of signal processing, such as detection or de-noising, it may be interesting to provide a second-moment characterization of a noise-corrupted signal in terms of uncorrelated random variables. Doing so, the noisy data could be described by its expansion into a weighted sum of known vectors by uncorrelated random variables. Depending on the choice of the basis vectors, some random variables are carrying more signal of interest information than noise ones. This is the case, for example, when a signal disturbed by a white noise is expanded using the Karhunen-Loève expansion. In these conditions, it is possible either to approximate the signal of interest by keeping only its associated random variables, or to detect a signal in a noisy environment with an analysis of the random variable power. The purpose of this tutorial is to present such an expansion, available for both the additive and multiplicative noise cases, and its application to detection and de-noising. This noisy random signal expansion is known as the stochastic matched filter, where the basis vectors are chosen so as to maximize the signal to noise ratio after processing.

This tutorial is divided into three parts:

- The first part concerns the theory itself: the stochastic matched filter theory will be described for 1-D discrete-time signals and its extension to 2-D discrete-space signals. Furthermore, a study will be realized on two different noise cases: the white noise case and the speckle noise case.
- In the second part, the stochastic matched filter will be described in a detection context and this method will be confronted with signals resulting from underwater acoustics. The results obtained are then compared with those resulting from the classical matched filter theory.
- In the last part, the stochastic matched filter will be presented in a de-noising

context. The de-noising being performed by a limitation to order Q of the noisy data expansion, two criteria to determine Q will be introduced. Experimental results on real SAS data are given to evaluate the performances of such an approach.

This tutorial is intended for people or scientists connected with 1-D/2-D signal or array processing, and interested to have a fly-over about these effective methods.

Presenter's Bio - Philippe Courmontagne

Philippe Courmontagne was born in 1970. He received the Ph. D. degree in Physics at the University of Toulon (France) in 1997. In 1999, he became Professor in a French electronic engineering school: the Institut Supérieur de l'Électronique et du Numérique (ISEN Toulon, France), in the field of signal processing and image processing. He joined in 2001 the Provence Materials and Microelectronics Laboratory (L2MP UMR CNRS 6137), which is a unit of the French national research center (CNRS). In 2005, he obtained his Habilitation (HDR - Habilitation to Supervise Research) for his works in the field of noisy signal expansion. In 2007, he has been elected to the degree of IEEE Senior Member in recognition of professional standing for his works in the field of signal de-noising (SAR, SAS images), signal detection in noisy environment and signal transmission.

T7 - ACOUSTICAL UNDERWATER COMMUNICATION PRINCIPLES

Salon London

The main objectives are to present fundamentals and state-of-the-art signaling and processing techniques suitable for acoustical underwater communications. Focus is on physical layer issues, but underwater networking issues are also covered. The whole range from biologically inspired signaling via information-theoretical inspired signaling to practical modulation schemes will be considered.

Outline of Material to be presented:

- Applications of acoustical underwater communications
- Channel characterization (channel measurement strategies, ray tracing, channel emulation, multipath propagation, delay spread, Doppler spread)
- Biologically inspired signaling (whale sounds)
- Information-theoretical inspired signaling (capacity bounds, superposition coding)
- Single-carrier transmission principles (PSK, QAM, CPM, error performance)
- Multi-carrier transmission principles (OFDM, generalized multi-carrier signaling)

- Synchronization and channel estimation
- Equalization
- Mobile underwater communications and adaptation to variable channel conditions
- Array processing (MIMO systems)
- Underwater networking

Presenter's Bio - Peter Adam Hoehner

1986 Master Degree (Dipl.-Ing.) in Electrical Engineering, RWTH Aachen University, Germany

1990 Doctoral Degree (Dr.-Ing.) in Electrical Engineering, University of Kaiserslautern, Germany

1986-1998 Research Assistant and Project Leader, German Aerospace Research Establishment (DLR), Oberpfaffenhofen

1992 Post-Doc, AT&T Bell Laboratories, Murray Hill, USA

1998-1999 Teaching Positions at the University of Erlangen-Nuremberg (Satellite Communications) and Bochum (Digital Modulation and Channel Coding)

Since 1998 Professor for Information and Coding Theory, University of Kiel, Germany

Visiting Researcher at the Australian National University, Canberra, Australia (1994), Communications Research Centre, Ottawa, Canada (1997), and the City University of Hong Kong (2002, 2008)

More than 150 publications in international journals and conference proceedings, more than 2000 citations of the Top10 papers. More than 40 patents in 12 patent families

Associated editor for IEEE Transactions on Communications (1999-2006)
Vice-chairman of the German Chapter of the IEEE Commun. Society (since 2004)

Proponent and member of the excellence cluster "The Future Ocean" of the University of Kiel

Member of the VDE/ITG Expert Committee 5.1 (since 2004)

Member of the VDE/ITG Technical Committee "Algorithms for Signal Processing" and "Applied Information Theory" (since 1999 and 2003)

Managing Director of the Institute of Electrical and Information Engineering of the University of Kiel (2006-2008)

Co-founder and Managing Director of ComSupport GbR (since 2005)

Experience in continuing education in engineering and science since 1994 (Carl Cranz Academy, Oberpfaffenhofen)

T8 - AUV TECHNOLOGY AND APPLICATION BASICS

Salon Danzig

AUV Application Basics is a short course that provides an overview of current AUV technologies and operations. The objective is to establish a basic understanding of what currently available AUV systems can provide and what are the best practices in use. The class is targeted at scientists interested in using AUVs for oceanographic applications. The attendee will gain basic understanding of AUV types, technologies, terminology, and navigation techniques, including discussion of the comparative strengths of AUVs and alternative methods of data collection. The attendee will also be provided an understanding of tradeoffs in AUV operations, including power estimation, endurance considerations, and mission structure to acquire the desired data sets. Key points are illustrated by applications and results from the Monterey Bay Aquarium Research Institute's (MBARI) Dorado AUV and other AUV operations. Topics include: Basic AUV technology, AUV at-sea Operation, Payload Considerations, Mission Planning, Upper and Mid-Water AUV missions, Benthic and Mapping AUV missions, Data Collection and Reduction, AUV Integration into Sampling Networks, and a look at coming AUV advances. The interactive format, using the materials provided, allows the attendee discussion time for relevance and demonstration purposes regarding real or potential AUV plans.

Intended Participants: This class is intended for scientists interested in applying AUVs to particular problems, persons interested in AUV applications and the impact of AUV technology, as well as graduates in oceanographic fields seeking a broad understanding regarding the application of AUV platforms.

Presenter's Bio - William J. Kirkwood

Bill is currently the Associate Director of Engineering at the Monterey Bay Aquarium Research Institute (MBARI) located in Monterey Bay, California. Bill has a BS in Mechanical Engineering and a MS in Computer Science which he has applied to controls and automation of electromechanical systems and robotics since 1978. Bill has been with MBARI for 16 years as a lead mechanical engineer and program manager developing the Tiburon remotely operated vehicle and Dorado class autonomous underwater vehicles. Bill's focus currently is developing underwater instrumentation for science to look at hydrates and anthropogenic CO₂ ocean acidification issues.

T11 - APPLICATION OF MICROSENSORS IN THE MARINE ENVIRONMENT

Salon Franzius

Microsensors have been developed to measure a wide range of substances and parameters. Microsensors have a minute tip diameter, typically only 1/10

of the human hair.

The small size gives the microsensors some extra-ordinary characteristics:

- they can penetrate into soft materials like seafloor sediment without disturbing the processes to be studied
- they can have a fast response (sub-second)
- they equilibrate with temperature very rapidly (sub-second)
- they consume very little analyte and are thus very insensitive to stirring
- they can work under extreme hydrostatic pressure (full ocean).

These characteristics make the sensors unique for a variety of applications in marine research and monitoring. The tutorial will explain in detail about

- The eddy correlation technique for oxygen flux measurements.
- Fast water column oxygen profiles. Fast profiling oxygen measurements in the water column require sensors with a fast response to oxygen and with a fast temperature equilibration.
- Microprofiling in seafloor sediments. Sediments are often highly stratified with layers with very different chemical conditions in close proximity.
- Ultra-low oxygen measurements. Some areas of the ocean have such a low oxygen concentration that it can be difficult to determine whether it is actually zero.

The target audience of the half-day tutorial is the marine environmental monitoring and research community. The tutorial will aim to provide the audience a basic understanding of the theoretical and practical aspects of microsensor technology, and the possibilities and limitations in the different applications will be discussed. Various in situ instruments carrying microsensors will be displayed. The tutorial will include a practical demonstration, which allows the audience to get hands-on experience with the technology.

Presenter's Bio - Lars R. Damgaard

Lars R. Damgaard made his Ph.D. thesis at the Department of Microbiology, University of Aarhus, Denmark, in 1997. After two years in a post.doc. position, Lars became a co-founder of Unisense A/S. Unisense is a company dedicated to providing microsensor technology to the world-wide scientific community, and Lars is responsible for the development of the electronics and in situ research equipment used in conjunction with Unisense microsensors. Furthermore, Lars has been the PI for Unisense on the COBO project, which is a EU project concerned with coastal benthic observatories as well as on a national Danish research project, BIOFLOW.

T13 - PRECISE BATHYMETRY USING MULTIBEAM ECHO-SOUNDER

Salon Scharoun

The lecture gives an introduction to operations with multibeam echosounder, as well as the positioning with high precision GNSS-systems and the attitude determination with inertial measurement systems and GNSS multi antennae arrays. The integration of the positioning, attitude determination and depth measurements in a modular real time system, the error budget and limiting conditions will be presented using examples from actual projects at the Hafen-City University Hamburg (HCU). Additionally the lecture is focused on aspects related to data processing, modeling and visualization.

The examples present projects onboard the survey craft LEVEL-A of the HCU: With the length of 7.5m and a draft of less than 50 cm the boat is optimized to operate in shallow waters. The LEVEL-A is mainly used for education and research purposes. The equipment installed onboard of LEVEL-A offers best conditions for practical exercises: RESON Multibeam SeaBat 8101, INNOMAR Parametric Sub-Bottom Profiler SES-2000 fan incl. Side-Scan, IxSEA motion sensor Octans III, GNSS-Javad-Gyro-4 (GPS, GLONASS), Marine Magnetics Mini Explorer, RESON Sound Velocity Probe SVP 15 and other instruments. Software packages as PDS 2000, QPS Qinsy and Qloud, WinProfile, ISE for SES-2000, Geo++ ® GNNET-RTK and CARIS HIPS/SIPS/GIS are available for survey planning, measuring, and data analysis.

Despite the high accuracy of all used sensors (position, heading, heave, roll, pitch and sound velocity), the main problem is to integrate these complementary sensors with the sonar systems with reference to timing and their relative locations to obtain reliable Digital Terrain Models (DTM). The data delivered by the IMSS components (GNSS-Javad-Gyro-4, Motion Sensor OctansIII, IMU Inertial Measurement Unit) are integrated by the soft-ware GNNET-RTK developed by Geo++ GmbH, Garbsen.

The examples will be taken from measurements for archaeology, wreck search, sand wave and gas detection in shallow waters in Germany.

Presenter's Bio - Volker Böder

Prof. D. Volker Böder was born in 1965 in Rotenburg/Wümme. He graduated in geodesy from the University Hannover in 1994. His doctoral thesis from 2002 at the University of Hannover is about the precise positioning and attitude determination in marine applications. He received his Assessor Degree from the Government of the Federal State of Lower Saxonia in 2005. Since 2005 he is professor for practical geodesy and hydrography at the HafenCity University, Hamburg (HCU). The M.Sc. Hydrography course at the HCU is English spoken. The course is certified with highest level Category A –academic- of the International Advisory Board of the FIG/IHO/ICA.

Volker Böder is board member of the German Hydrography Society (Deutsche Hydro-graphische Gesellschaft, DHyG) and editor of the “Hydrographische Nachrichten”. Additionally he is member of the working group AK3 –measuring methods and systems- of the DVW. In the last years as well as in 2009 Prof. Böder gave a one-week-lecture at the UPM Madrid, Spain. Each year he organizes the International Hydrography Summer Camp, which is free for all interested students.

T14 - APPLIED MODEL-BASED SIGNAL PROCESSING – CLASSICAL, MODERN AND BAYESIAN TECHNIQUES **Salon Bergen**

In this course, we teach basic concepts in model-based signal processing using an applied approach. Participants are exposed to many simulation examples to reinforce the theoretical concepts introduced during the lectures. The student is assumed to have basic knowledge in linear systems, probability and random processes. The tutorial is designed to take the participant from stochastic model development through the heart of physics-based stochastic modeling - the Gauss-Markov state-space model. Estimation basics will be discussed including maximum likelihood and maximum a-posteriori estimators. The state-space model-based processor (MBP) or equivalently Kalman filter will be investigated in order to develop an intuition for constructing successful MBP designs using the “minimum error variance approach”. Practical aspects of the MBP will be developed to provide a reasonable approach for design and analysis. Overall MBP Design Methodology will be discussed. Extensions of the MBP follow for a variety of cases including nonlinear filtering using the classical extended Kalman filter the modern unscented Kalman filter and the current Bayesian particle filter. Applications and case studies will be discussed throughout the lectures. Practical aspects of MBP design will be discussed for “tuning” and processing.

In summary, this course not only provides the participants with the essential theory underlying model-based signal processing techniques, but applied design and analysis. Course Materials: Master copies of the viewgraphs will be provided to the participants.

Presenter’s Bio - James V. Candy

James V. Candy is the Chief Scientist for Engineering and former Director of the Center for Advanced Signal & Image Sciences at the University of California, Lawrence Livermore National Laboratory. Dr. Candy received a commission in the USAF in 1967 and was a Systems Engineer/Test Director from 1967 to 1971. He has been a Researcher at the Lawrence Livermore National Laboratory since 1976 holding various positions including that of Project

Engineer for Signal Processing and Thrust Area Leader for Signal and Control Engineering. Educationally, he received his B.S.E.E. degree from the University of Cincinnati and his M.S.E. and Ph.D. degrees in Electrical Engineering from the University of Florida, Gainesville. He has been an Adjunct Professor at San Francisco State University, University of Santa Clara, and UC Berkeley, Extension teaching graduate courses in signal and image processing. He is an Adjunct Full-Professor at the University of California, Santa Barbara. Dr. Candy is a Fellow of the IEEE and a Fellow of the Acoustical Society of America (ASA) and recently elected as a Life Member (Fellow) at the University of Cambridge (Clare Hall College). He is a member of Eta Kappa Nu and Phi Kappa Phi honorary societies. He was elected as a Distinguished Alumnus by the University of Cincinnati. Dr. Candy received the IEEE Distinguished Technical Achievement Award for the “development of model-based signal processing in ocean acoustics.” Dr. Candy was selected as a IEEE Distinguished Lecturer for oceanic signal processing as well as presenting an IEEE tutorial on advanced signal processing available through their video website courses. He was nominated for the prestigious Edward Teller Fellowship at Lawrence Livermore National Laboratory. Dr. Candy has recently been awarded the Interdisciplinary Helmholtz-Rayleigh Silver Medal in Signal Process/Underwater Acoustics by the Acoustical Society of America for his technical contributions. He has published over 200 journal articles, book chapters, and technical reports as well as written three texts in signal processing with a fourth in press. He was the General Chairman of the inaugural 2006 IEEE Nonlinear Statistical Signal Processing Workshop held at the Corpus Christi College, University of Cambridge. He has presented a variety of short courses and tutorials sponsored by the IEEE and ASA in Applied Signal Processing, Spectral Estimation, Advanced Digital Signal Processing, Applied Model-Based Signal Processing, Applied Acoustical Signal Processing, Model-Based Ocean Acoustic Signal Processing and most recently Bayesian Signal Processing for IEEE Oceanic Engineering Society/ASA. He has also presented short courses in Applied Model-Based Signal Processing for the SPIE Optical Society. He is currently the IEEE Chair of the Technical Committee on “Sonar Signal and Image Processing” and was the Chair of the ASA Technical Committee on “Signal Processing in Acoustics” as well as being an Associate Editor for Signal Processing of ASA (on-line JASAE). He has recently been nominated for the Vice Presidency of the ASA as well as the Administrative Committee of IEEE OES. His research interests include Bayesian estimation, identification, spatial estimation, signal and image processing, array signal processing, nonlinear signal processing, tomography, sonar/radar processing and biomedical applications.

TECHNICAL PROGRAM

Tuesday, May 12 (13h30 – 15h10)

Focke-Wulf Saal

10.4-1 Autonomous underwater vehicles 1

Co-Chairs: António Pascoal, Instituto Superior Tecnico (IST), Lisbon

Exploring Beneath the PIG Ice Shelf with the Autosub3 AUV
Stephen McPhail, National Oceanography Centre, Southampton

Air Launched Platforms - a new approach for underwater vehicles
Peter Stevenson, National Oceanography Centre, Southampton

Comparison between results obtained with Thetis, a real-time multi-vehicles hardware-in-the-loop simulator, and results obtained during sea trials
Olivier Parodi, University of Montpellier, LIRMM

Towards AUV docking on sub-sea structures
Szymon Krupinski, Cybernetix SA

Tuesday, May 12 (13h30 – 15h10)

Lloyd Saal

BRE3-1 Ocean Observing Systems and Strategies 1

Co-Chairs: Alan Chave, Woods Hole Oceanographic Institution
Toshihiko Kanazawa, The University of Tokyo

Development of Compact Ocean Bottom Cabled Seismometers System for Spatially Dense Observation on Sea Floor and First Installation Plan
Toshihiko Kanazawa, The University of Tokyo

The IEO Coastal Observing System at the Southern Bay of Biscay, new real-time development: The ocean-meteorological AGL buoy.
Alicia Lavín, Instituto Español de Oceanografía, Santander

TasMAN: The Tasmanian Marine Analysis Network
Gregory Timms, CSIRO, Tasmanian ICT Centre

System Engineering at the edge of a cabled ocean observatory
Peter Phibbs, University of Victoria

Technical Program

Cyberinfrastructure for the US Ocean Observatories Initiative: Enabling Interactive Observation in the Ocean

Alan Chave, Woods Hole Oceanographic Institution

Tuesday, May 12 (13h30 – 15h10)

Salon Bergen

10.1-1 Vehicle design 1

Co-Chairs: Massimo Caccia, National Research Council (CNR), ISSIA
Carolin Lange, Deutsches Zentrum für Luft- und Raumfahrt

Development of a low-cost autonomous oceanographic observation vehicle
Spartacus Castro, Technical University of Catalonia

A two-fold strategy for designing minimal fuel consumption, superior seakeeping highly maneuverable marine vessels based on ASAP HULL technology and SONTAG non-linear feedback stabilization

Joule Mikhael, Alexandria University, Faculty of Engineering

Transfer, Adaptation and Further Development of Terrestrial Ocean Vehicle Technology for the Exploration of the Jovian Moon Europa

Carolin Lange, Deutsches Zentrum für Luft- und Raumfahrt

Prototype Development of the SQX-1 Autonomous Underwater Vehicle

David Shea, Marport Canada Inc.

An overall Pressure Tolerant Underwater Vehicle: DNS Pegel

Carl Thiede, Technical University Berlin

Tuesday, May 12 (13h30 – 15h10)

Salon Danzig

3.3-1 Oceanographic Instrumentation, buoys and cables 1

Co-Chairs: Peter Linke, IFM-GEOMAR

Optical measurements of nitrate and H₂S concentrations in Baltic waters
Ralf Prien, Leibniz Institute for Baltic Sea Research (IOW)

Cabled Observatory Technology for Ocean Acidification Research

William Kirkwood, Monterey Bay Aquarium Research Institute

Technical Program

Development of a new Lagrangian float for studying coastal marine ecosystems

Alexander Schwithal, Technical University of Braunschweig

11,000m class Free Fall Mooring System

Takashi Murashima, JAMSTEC

Biofouling protection for marine underwater observatories sensors

Laurent Delauney, IFREMER

Tuesday, May 12 (13h30 – 15h10)

Salon Franzius

2.8-1 Acoustic Telemetry and Communication 1

Co-Chairs: Andreja Radošević, University of California San Diego

Frequency-Domain Turbo Equalization for MIMO Underwater Acoustic Communications

Jian Zhang, Missouri University of Science and Technology

Receiver Comparisons on an OFDM Design for Doppler Spread Channels

Sean Mason, University of Connecticut

Divergent Beam Shaping for High Data-Rate Underwater Communications

Craig Benson, University of New South Wales

Cognitive Intelligence in UAC Channel Parameter Identification, Measurement, Estimation, and Environment Mapping

Sadia Ahmed, University of South Florida

Underwater Acoustic Sparse Aperture System Performance: Using Transmitter Channel State Information for Multipath & Interference Rejection

Lisa Burton, Massachusetts Institute of Technology

Tuesday, May 12 (13h30 – 15h10)

Salon London

BRE1 Ecology versus Economy

Co-Chairs: Jan Schulz, Alfred Wegener Institute, Bremerhaven

Mara Schmiing, University of the Azores

Technical Program

Geopolitical and eco-economical aspects of natural resources management in Baltic Sea region

Vladimir Anikiev, Russian Ecological Independent Expertise

Quantitative analysis of Omega-3 aliphatic acid from Schizochytrium grown under different spectral photo emissions

Jose Oclarit, Mountain View College

Cost Benefit Analysis in the era of Sustainable Development

Pedro Simal, University of Cantabria

Integrating recent and future marine technology in the design of Marine Protected Areas - the Azores as case study

Mara Schmiing, University of the Azores

Tuesday, May 12 (13h30 – 15h10)

Salon Scharoun

2.1-1 Sonar Signal Processing 1

Co-Chairs: Andrea Caiti, University of Pisa, DSEA

Timothy Duda, Woods Hole Oceanographic Institution

Sensing the underwater sound field produced by a moving airborne signal source

Brian Ferguson, Defence Science & Technology Organisation

An Underwater Noise Reduction Algorithm using Frame-Based Wavelets

Hui Ou, University of Hawaii at Manoa

Variability of Available Capacity due to the Effects of Depth and Temperature in the Underwater Acoustic Communication Channel

Anuj Sehgal, Jacobs University Bremen

Toward in situ detection of algae species

Florent Colas, IFREMER

Sonar-based AUV localization using an improved particle filter algorithm

Francesco Maurelli, Heriot-Watt University

Tuesday, May 12 (15h40 – 17h20)

Focke-Wulf Saal

10.4-2 Autonomous underwater vehicles 2

Co-Chairs: James Ferguson, International Submarine Engineering Ltd.

GALATEA, a highly versatile autonomous underwater vehicle with bio-mechanical propulsion

Dick Simons, Delft University of Technology

Portability Investigation of Space Docking Techniques for AUV Docking

Francesco Maurelli, Heriot-Watt University

Cooperating AUV teams: Adaptive area coverage with space-varying communication constraints

Andrea Caiti, University of Pisa, DSEA

Measuring light attenuation with a compact Optical Emission Spectrometer and CTD mounted on a low cost AUV

Klaas Hartmann, CSIRO, Tasmanian ICT Centre

Tuesday, May 12 (15h40 – 17h20)

Lloyd Saal

BRE3-2 Ocean Observing Systems and Strategies 2

Co-Chairs: Mal Heron, James Cook University

Developing the Ocean Networks Canada Centre for Enterprise and Engagement

Martin Taylor, Ocean Networks Canada

Autonomous Bathymetry for Risk Assessment with ROAZ Robotic Surface Vehicle

Hugo Ferreira, Instituto Superior de Engenharia do Porto

COSYNA, an Integrated Coastal Observation System for Northern and Arctic Seas

Rolf Riethmüller, GKSS Research Centre Geesthacht

Technical Program

Tuesday, May 12 (15h40 – 17h20)

Salon Bergen

10.1-2 Vehicle design 2

Co-Chairs: Stephen Wood, Florida Institute of Technology
Cesar Peña Cortes, Univ. of Madrid and Univ. of Pamplona

Aluminum hull USV for coastal water and seafloor monitoring
Massimo Caccia, National Research Council (CNR), ISSIA

Underwater parallel robot for oceanic measuring and observation - REMO I:
Development and navigation control advances
Roque Saltaren, Technical University of Madrid

Design, simulation and experimental results of Taipan 300, a new Autonomous
Underwater Vehicle prototype.
Vincent Creuze, University of Montpellier, LIRMM

Empirically Computation of hydrodynamic derivatives of an AUV
Mojtaba Barjasteh, Sadra HydroIndustry Co.

Development of a Multi-drive Submersible Platform for deep seabed research
Tjasa Boh, University of Southern Queensland

Tuesday, May 12 (15h40 – 17h20)

Salon Danzig

3.3-2 Oceanographic Instrumentation, buoys and cables 2

Co-Chairs: Peter Linke, IFM-GEOMAR

Heat flow measurements with the newly designed FIELAX Heat Flow Probe.
Wiebke Nehmiz, FIELAX GmbH

Smart sensor metamodel for deep sea observatory
Oussama Kassem Zein, Ecole Nationale Supérieure d'Ingénieurs

Underway CTD - A new tool for underway soundspeed profiling
Jochen Klinke, The Oceanscience Group

New instruments to monitor coastal sea water masses according to European
Water Framework Directive, Trophimatique project
Michel Repecaud, IFREMER

Technical Program

Lightframe On-sight Key species Investigation (LOKI) - The art of imaging tiny plankton species on-the-fly

Jan Schulz, Alfred Wegener Institute, Bremerhaven

Tuesday, May 12 (15h40 – 17h20)

Salon Franzius

2.8-2 Acoustic Telemetry and Communication 2

Co-Chairs: Sean Mason, University of Connecticut
Wen Xu, Zhejiang University

Statistical Characterization and Capacity of Shallow Water Acoustic Channels
Andreja Radosevic, University of California San Diego

Experimental studies of time-reversal underwater acoustic communications
Menglu Xia, Zhejiang University

On the use of interwoven order of oncoming packets for reliable underwater acoustic data transfer
Kebkal, EvoLogics GmbH

Implementation and Evaluation of Multihop ARQ for Reliable Communications in Underwater Acoustic Networks
Alvin Valera, Institute for Infocomm Research (I2R), Singapore

Distance Awareness Scheduling for Single-Hop Underwater Ad-Hoc Network
Omar Aldawibi, Newcastle University

Tuesday, May 12 (15h40 – 17h20)

Salon London

BRE5 Renewable Energy

Co-Chairs: Oliver Zielinski, IMARE Bremerhaven

Innovative Wave Power Generation System Using Electroactive Polymer Artificial Muscles
Seiki Chiba, SRI International

Tidal Stream Power Technology - State of the Art
Jeremy King, Bristol University

Technical Program

Cabled Observatory Technology for Ocean Renewable Energy Devices
Harald Grob, OceanWorks, Canada

Tuesday, May 12 (15h40 – 17h20)

Salon Scharoun

2.1-2 Sonar Signal Processing 2

Co-Chairs: James Candy, Lawrence Livermore National Laboratory

An Underwater Target Classification Scheme Based on Wigner-Ville Distribution and Gustafson-Kessel Clustering

Hui Ou, University of Hawaii at Manoa

Acoustic Wave Processing and target detection

Hossein Shahbazi, Institute of Engineering Research

Finite Element Modeling of Sonar Domes with Noise for Transducer Arrays in Sea Environment

Hind Mestouri, Institut Sup. de l'Electronique et du Numérique, Brest

Evolving Radial Basis Function Neural Network with Hausdorff Similarity Measure for SONAR Signals Detection/ Classification

Hossein Peyvandi, Scientific Applied Telecommunication College

Wednesday, May 13 (08h30 – 10h10)

Focke-Wulf Saal

10.4-3 Autonomous underwater vehicles 3

Co-Chairs: Stephen McPhail, Nat. Oceanography Centre, Southampton

UAV and AUVs Coordination for Ocean Exploration

P.B. Sujit, University of Porto, Faculty of Engineering, LSTS

MR-X1 – An AUV Equipped with A Space Distributed CPU System and A Satellite Telecontrol Interface

Hiroshi Yoshida, JAMSTEC

Sensor-based problems and techniques for Autonomous Underwater Vehicles

Bernardo Maciel, University of Porto, Faculty of Engineering

Technical Program

A Simulation Environment for Autonomous Underwater Vehicles
Hans-Ulrich Kobialka, Fraunhofer IAIS

AUV docking system for existing underwater control panel
Panagiotis Sotiropoulos, European Commission JRC, ISPRA

Wednesday, May 13 (08h30 – 10h10)

Lloyd Saal

BRE3-3 Ocean Observing Systems and Strategies 3

Co-Chairs: Wilhelm Petersen, GKSS Research Centre Geesthacht
José Pinto, University of Porto, LSTS

All the year round investigations of the current profiles variability near the Curonian Spit (South-East Baltic)
Vladimir Gorbatsky, Krylov Shipbuilding Research Institute

Large Scale Data Collection Using Networks of Heterogeneous Vehicles and Sensors
José Pinto, University of Porto, Faculty of Engineering, LSTS

FerryBox - Application of Continuous Water Quality Observations along Transects in the North Sea
Wilhelm Petersen, GKSS Research Centre Geesthacht

Tsunami Observatory for South Korea
Klaus Schleisiek, SEND Off-Shore Electronics GmbH

Installation method of high-quality seismic observation in the seafloor
Sho Kaneko, JAMSTEC

Wednesday, May 13 (08h30 – 10h10)

Salon Bergen

10.2-1 Vehicle navigation 1

Co-Chairs: Lutz Richter, German Aerospace Center, DLR
Yoshitaka Watanabe, JAMSTEC

Terrain based localization for pinpoint observation of deep seafloors
Takeshi Nakatani, The University of Tokyo

Technical Program

A MOOS-Based Online Trajectory Re-planning System For AUVs
Matko Barisic, University of Zagreb

Distance Keeping for Underwater Vehicles - Tuning Kalman Filters Using Self-Oscillations
Nikola Miskovic, University of Zagreb

A tracking of AUV with integration of SSBL acoustic positioning and transmitted INS data
Yoshitaka Watanabe, JAMSTEC

Subsea Positioning with Tight Coupling of Acoustic and Inertial Technologies
Pierre-Yves Morvan, IXSEA

Wednesday, May 13 (08h30 – 10h10)

Salon Danzig

3.3-3 Oceanographic Instrumentation

Co-Chairs: Ralf Prien, Leibniz Institute for Baltic Sea Research (IOW)
Thomas O'Reilly, Monterey Bay Aquarium Research Institute

Automated Nucleic Biosensors – A Key to High Resolution Monitoring of Marine Phytoplankton
Katja Metfies, GKSS Research Centre Geesthacht

Instrument interfaces for interoperable ocean sensor networks
Thomas O'Reilly, Monterey Bay Aquarium Research Institute (MBARI)

PACT - a bottom pressure based, compact deep-ocean tsunameter with acoustic surface coupling
Andreas Macrander, Alfred Wegener Institute, Bremerhaven

New Technology for Ecosystem-Based Management: Marine Monitoring with the ORCA Kilroy Network
Eric Thosteson, Ocean Research & Conservation Association

Real-time procedures implemented within coastal HF radar system in the northern Adriatic
Ivica Vilibic, Institute of Oceanography and Fisheries, Croatia

Technical Program

Wednesday, May 13 (08h30 – 10h10)

Salon Franzius

2.8-3 Acoustic Telemetry and Communication 3

Co-Chairs: Peter Hoeher, ComSupport GbR
Pierre-Philippe Beaujean, Florida Atlantic University

Iterative Equalization for Underwater Acoustic Channels using Bit Interleaved Coded Modulation and Decision Feedback Equalization
Chintan Shah, Newcastle University

Mitigation of Intercarrier Interference in OFDM Systems over Underwater Acoustic Channels
Kai Tu, Arizona State University

Shallow water, multi-user navigation and telemetry, performance issues and practical demonstration
Jonathan Davies, Sonardyne International Ltd

Adaptive Acoustic Underwater Communications based on Generalized Multi-Carrier Interleave-Division Multiplexing
Peter Hoeher, ComSupport GbR

Wednesday, May 13 (08h30 – 10h10)

Salon London

BRE6 Adanced Technology for Recources Exploration

Co-Chairs: Tim Freudenthal, University of Bremen, MARUM

High Resolution, Deep-tow Seismic Survey to Investigate Methane Hydrate-bearing Sediments, Nankai Trough, Offshore, JAPAN
Eiichi Asakawa, JGI, Inc., Tokyo

Methane hydrate detection with marine electromagnetic surveys: case studies off Japan coast
Tada-nori Goto, Kyoto University

Comparison of machine vision based methods for online in situ oil seep detection and quantification
Bjoern Saworski, Institute for Marine Resources (IMARE) GmbH

Technical Program

Detection and identification of hydrocarbons in marine waters using time-resolved laser-fluorescence: Set-up and first results of a new submersible sensor

Peter Rohde, Hochschule Bremerhaven

Shallow Drilling in the Deep Sea: The Sea Floor Drill Rig MeBo

Tim Freudenthal, University of Bremen, MARUM

Wednesday, May 13 (08h30 – 10h10)

Salon Scharoun

2.7 Sonar Imaging

Co-Chairs: Philippe Courmontagne, Institut Supérieur de l'Electronique et du Numérique (ISEN), Toulon

An improvement on SAS image formation

Philippe Courmontagne, ISEN, Toulon

Acoustic Stereo Imaging (ASI) System

Hassan Assalih, Heriot-Watt University

GPU-based Simulation of Side-looking Sonar Images

Enrique Coiras, NATO Undersea Research Centre

Side Scan Sonar Image Resolution and Automatic Object Detection, Classification and Identification

Wolfgang Jans, Free University of Berlin, FWG

Source number estimation using eigenspace in direction of arrival (DOA) estimate and its application in sonar

WeiQing Zhu, The Chinese Academy of Sciences

Wednesday, May 13 (10h40 – 12h00)

Focke-Wulf Saal

10.4-4 Autonomous underwater vehicles 4

Co-Chairs: Lutz Richter, German Aerospace Center, DLR

A New Concept for an Obstacle Avoidance System for the AUV

Mike Eichhorn, National Research Council, Canada

Technical Program

Full Function Air Transportable AUV Joins the Fugro Fleet
Donald Hussong, Fugro Seafloor Surveys, Inc.

Collaborative Mapping with Autonomous Underwater Vehicles in Low-Bandwidth Conditions
Benjamin Johnson, University of Idaho

A Fuzzy Logic Resource Optimizer for a Fleet of Autonomous Vehicles in Low-Bandwidth Conditions
Benjamin Johnson, University of Idaho

Multi AUV control in an operational context: a leader-follower approach
Rudolf Haraksim, IFREMER

Wednesday, May 13 (10h40 – 12h00)

Lloyd Saal

BRE3-4 Ocean Observing Systems and Strategies 4

Co-Chairs: Mal Heron, James Cook University

HF Radar Role in an Integrated Ocean Observing System
Mal Heron, James Cook University

ROSE: development and demonstration of a 'Mobile Response Observatory' prototype for subsea environmental monitoring
Jean Marvaldi, IFREMER

Precision Timing in the NEPTUNE Canada Network
Stephen Lentz, Lentz Telecommunications Strategies LLC

Kilo Nalu Cabled Observatory: A Window into the Hawaiian Coastal Environment
Geno Pawlak, University of Hawaii

Wednesday, May 13 (10h40 – 12h00)

Salon Bergen

10.2-2 Vehicle navigation 2

Co-Chairs: Stephen Wood, Florida Institute of Technology
Vincent Creuze, University of Montpellier, LIRMM

Technical Program

Portable control console for autonomous ocean-going vehicles
David Hlavac, University of Porto, Faculty of Engineering, LSTS

Manoeuvre Based Mission Control System for Autonomous Surface Vehicle
Nuno Dias, Instituto Superior de Engenharia do Porto

Pose-Based SLAM with Probabilistic Scan Matching Algorithm using a Mechanical Scanned Imaging Sonar
Angelos Mallios, University of Girona

Vision Based Localization System for AUV Docking on Subsea Intervention Panels
Tomeu Palmer, Marexi Mediterranean

Coordinated Path following Control of Multiple Nonholonomic Vehicles
Xianbo Xiang, University of Montpellier, LIRMM

Wednesday, May 13 (10h40 – 12h00)

Salon Danzig

4.4 Coastal radars

Co-Chairs: Thomas Helzel, Helzel Messtechnik GmbH
Eric Gill, Memorial University of Newfoundland

High resolution current and bathymetry information determined by nautical x-band radar in shallow waters
Katrin Hessner, OceanwaveS GmbH

Sharing our experience using wave theories inversion for the determination of the local depth
Stylianos Flampouris, GKSS Research Centre Geesthacht

Accuracy and Reliability of Ocean Current and Wave Monitoring with the Coastal Radar "WERA"
Thomas Helzel, Helzel Messtechnik GmbH

Sediment Modeling based on Radar Observed Surface Hydrodynamics
Stephan Sedlacek, GKSS-Forschungszentrum

Technical Program

A Simulation Technique for High Frequency Doppler Spectra and Comparison with High-Bandwidth WERA Data

Jianjun Zhang, Memorial University of Newfoundland

Wednesday, May 13 (10h40 – 12h00)

Salon Franzius

2.8-4 Acoustic Telemetry and Communication 4

Co-Chairs: Milica Stojanovic, Northeastern University
Peter Hoeher, ComSupport GbR

Design of Receiver Front-End with 25kHz Carrier Frequency and 5 kHz Symbol Rate for Communication System

Seung-Geun Kim, Korea Ocean Research & Development Institute

Sparse Channel Estimation for Multicarrier Underwater Acoustic Communication: From Subspace Methods to Compressed Sensing

Christian Berger, University of Connecticut

High Bit Rate Communication Through Metallic Structures Using Electromagnetic Acoustic Transducers

David Graham, Newcastle University

A Performance Study of the High-Speed, High-Frequency Acoustic Uplink of the HERMES Underwater Acoustic Modem

Pierre-Philippe Beaujean, Florida Atlantic University

Wednesday, May 13 (10h40 – 12h00)

Salon London

6.5 Marine life, ecosystems, and pollution monitoring

Co-Chairs: Melanie Beck, University of Oldenburg
Todd Morrison, Nobska

Development of Ballast Water Treatment System Based on Electrochemical Disinfection Technology

Eun-Chan Kim, Korea Ocean Research & Development Institute

Issues and Preliminary Results in Oil Spill Detection Using Optical Remotely Sensed Images

Linda Corucci, University of Pisa

Technical Program

Topic-based habitat classification using visual data

Oscar Pizarro, Univ. of Sydney, Australian Centre for Field Robotics

An approach for tracking oil slicks by using active contours on satellite images

Sandra Robla, University of Cantabria

Marine biological baseline study in Igaliku fjord, Greenland

Fredrik Søreide, Norwegian University of Science and Technology

Wednesday, May 13 (10h40 – 12h00)

Salon Scharoun

2.7A Sonar Imaging ATLAS

Co-Chairs: Arne Kraft, Atlas Elektronik GmbH

Ursula Hölscher-Höbing, Atlas Elektronik GmbH

On the Influence of Positioning Errors on Tomography-Based Sonar Imaging Systems

Fritz Boschen, Bergische Universität Wuppertal

Quality assessment of synthetic aperture sonar images

Christian Debes, Technical University Darmstadt

Fast High Resolution Sonar Imaging using High Bandwidth Transducers and Frequency Domain Compounding

Robert Lemor, Fraunhofer IBMT

3D-Sonar Image Formation and Shape Recognition Techniques

Dieter Kraus, Hochschule Bremen

Multi-Beam/Multi-Aspect Image Processing for AUV Application

Ursula Hölscher-Höbing, Atlas Elektronik GmbH

Wednesday, May 13 (13h30 – 15h10)

Focke-Wulf Saal

10.4GA Atlas GREX A

Co-Chairs: António Pascoal, Instituto Superior Tecnico (IST), Lisbon

Jörg Kalwa, Atlas Elektronik GmbH

Technical Program

Obstacle Avoidance for Multiple Unmanned Marine Vehicles (MUMVs) in Close Formation

Thomas Glotzbach, Ilmenau University of Technology

Relative positioning of multiple underwater vehicles in the GREX project

Robert Engel, Atlas Elektronik GmbH

Cooperative Autonomous Marine Vehicle Motion Control in the scope of the EU GREX Project: Theory and Practice

António Pascoal, Instituto Superior Tecnico (IST), Lisbon

Wednesday, May 13 (13h30 – 15h10)

Lloyd Saal

BRE7 Estuary systems and Wadden Seas

Co-Chairs: Götz Flöser, GKSS Research Centre Geesthacht

Observatory in the Wadden Sea: Nutrient cycling and export to the North Sea

Melanie Beck, University of Oldenburg

Monitoring river estuaries and coastal areas using TerraSAR-X data

Stephan Brusch, German Aerospace Center (DLR),

Automated measuring stations in the German Wadden Sea

Götz Flöser, GKSS Research Centre Geesthacht

Wednesday, May 13 (13h30 – 15h10)

Salon Bergen

10.2-3 Vehicle navigation 3

Co-Chairs: Arne Hoof, IXSEA GmbH, Frankfurt

Full-depth ROV ABISMO and its transponder

Takao Sawa, JAMSTEC

Doppler Water-Track Aided Inertial Navigation for Autonomous Underwater Vehicles

Oyvind Hegrehaes, Kongsberg Maritime

Technical Program

Preventing Extended Kalman Filter Instabilities During Two Transponder Long Baseline Navigation with Real Time Fuzzy Logic Parameter Adjustment
Jesse Pentzer, University of Idaho

Path Planning for Multiple Marine Vehicles
Andreas Häusler, Instituto Superior Tecnico (IST), Lisbon, Portugal

Wednesday, May 13 (13h30 – 15h10)

Salon Danzig

3.2 Current Measurement technology

Co-Chairs: Albert Williams, Woods Hole Oceanographic Institution

High-Resolution Current Measurements From Space With TerraSAR-X Along-Track InSAR
Roland Romeiser, University of Miami

The variable-buoyancy drifting DIMES Shearwater instrument
Timothy Duda, Woods Hole Oceanographic Institution

Measuring high and low waves with HF radar
Lucy Wyatt, University of Sheffield

Current and Wave Measurements in Support of Shallow Water Environmental Modeling
James Churchill, Woods Hole Oceanographic Institution

Simulation of tsunami signatures in ocean surface current maps measured by HF radar
Anna Dzvonkovskaya, University of Hamburg

Wednesday, May 13 (13h30 – 15h10)

Salon Franzius

7.4 Marine optics technology and communication

Co-Chairs: John Watson, University of Aberdeen

Studying the behaviour of Norway lobster using RFID and Infrared Tracking technologies
David Sarrià, Technical University of Catalonia (UPC), SARTI

Technical Program

Optical Communication for Underwater Wireless Sensor Networks: a VHDL-implementation of a Physical Layer 802.15.4 Compatible

Davide Brizzolara, University of Genoa

An Efficient Transmission Scheme for Underwater Sensor Networks

Soonchul Park, Kyungpook National University

A Data Link Layer in Support of Swarming of Autonomous Underwater Vehicles

Daladier Jabba Molinares, University of South Florida

Wednesday, May 13 (13h30 – 15h10)

Salon London

5.1 Data access, handling and visualization

Co-Chairs: Benoît Pirenne, University of Victoria, NEPTUNE project
Are Willumsen, Kongsberg Maritime

Biigle - Web 2.0 enabled labelling and exploring of images from the Arctic deep-sea observatory HAUSGARTEN

Jörg Ontrup, Bielefeld University

Keeping Pace with Technology Through the Development of an Intuitive Data Fusion, Management, Analysis & Visualization Software Solution

Tim Pauly, Myriax Software Pty. Ltd.

The Data Management System for the VENUS and NEPTUNE Cabled Observatories

Benoît Pirenne, University of Victoria, NEPTUNE project

The joys of smoothing

Are Willumsen, Kongsberg Maritime

Wednesday, May 13 (15h40 – 17h20)

Focke-Wulf Saal

10.4GB Atlas GREX B

Co-Chairs: Jörg Kalwa, Atlas Elektronik GmbH
António Pascoal, Instituto Superior Tecnico (IST), Lisbon

Technical Program

GREX sea trials: first experiences in multiple underwater vehicle coordination based on acoustic communication

Lorenzo Brignone, IFREMER

The GREX-Project: Coordination and control of cooperating heterogeneous unmanned systems in uncertain environments

Jörg Kalwa, Atlas Elektronik GmbH

A communication infrastructure for cooperative operation of a fleet of heterogeneous autonomous marine vehicles: Concepts and developments within the GREX project

João Alves, Orange Energy Lda. and Blue Edge Lda., Portugal

Wednesday, May 13 (15h40 – 17h20)

Lloyd Saal

6.1 Ocean Sciences and Meteorology

Co-Chairs: Nicolas Nowald, University of Bremen, MARUM

Measurements of high concentration sediment plume in the estuary with strong tidal currents

Hwa Chien, National Central University

In-situ sinking speed measurements of marine snow aggregates acquired with a settling chamber mounted to the Cherokee ROV

Nicolas Nowald, University of Bremen, MARUM

Application of a remote controlled hammering drill from space to deep sea

Lutz Richter, German Aerospace Center (DLR)

Physical controls of cold seep methane emissions

Peter Linke, IFM-GEOMAR

Deepwater archaeology - status and potential

Fredrik Søreide, Norwegian University of Science and Technology

Wednesday, May 13 (15h40 – 17h20)

Salon Bergen

10.2-4 Vehicle navigation 4

Co-Chairs: Vincent Rigaud, IFREMER

Technical Program

A Conical Laser Light-Sectioning Method for Navigation of Autonomous Underwater Vehicles for Internal Inspection of Pipelines

Unnikrishnan Viswambharan, The University of Tokyo

Terrain Referencing for Autonomous Navigation of Underwater Vehicles

Colin Morice, University of Southampton

Radar Based Collision detection developments on USV ROAZ II

Carlos Almeida, Instituto Superior de Engenharia do Porto

Wednesday, May 13 (15h40 – 17h20)

Salon Franzius

2.2 Array signal processing and array design

Co-Chairs: Andrea Caiti, University of Pisa, DSEA

James Candy, Lawrence Livermore National Laboratory

Non-Perfect Channel Estimation in OFDM-MIMO-based Underwater Communications

Knut Grythe, SINTEF ICT, Trondheim

Non-linear, adaptive array processing for underwater source localization and sonar interference suppression

Elizabeth Hoppe, Virginia Polytechnic Institute and State University

True time-delay bandpass beamforming: A new implementation

Wen Xu, Zhejiang University

Synthetic Elements for Moving Line Arrays

Mary Johnson, Naval Underwater Weapons Center (NUWC), Newport

Distributed Underwater Source Location Estimation Using a Multi-Array Network

Michael Roan, Virginia Polytechnic Institute and State University

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Salon London

5.3 Numerical modelling

Co-Chairs: Shreenivas Londhe, Vishwakarma Institute of Information Technology, Pune

Technical Program

Towards predicting water levels using artificial networks

Shreenivas Londhe, Vishwakarma Inst. of Information Tech., Pune

Development of a GIS-based oil spill risk assessment system

Sonia Castanedo, University of Cantabria

Introducing marine climate variability into life cycle management of coastal and offshore structures

Inigo Losada, University of Cantabria

Real time Sidescan Simulator and Applications

Yan Pailhas, Heriot-Watt University

Web-based GIS dedicated for marine environment surveillance and monitoring

Lukasz Kaminski, Gdansk University of Technology

Wednesday, May 13 (15h40 – 17h20)

Salon Scharoun

8.3-1 Marine law and policy 1

Co-Chairs: Gerd Winter, University of Bremen

Douglas Burnett, Squire, Sanders, & Dempsey L.L.P.

Offshore Wind Farm Siting In Germany and the United States: Legal and Policy Impediments and Supports

Michelle Portman, Woods Hole Oceanographic Institution

Under-Ice Seabed Mapping with AUVs

James Ferguson, International Submarine Engineering Ltd.

Deep Sea Observatories and International Law

Douglas Burnett, Squire, Sanders, & Dempsey L.L.P.

Place of Refuge for Ships in Need of Assistance - Methodological Approach and Croatian Concept

Zeljko Bradaric, Hydrographic Institute of the Republic of Croatia

Thursday, May 14 (08h30 – 10h10)

Focke-Wulf Saal

3.1 Automatic Control

Co-Chairs: John Potter, NATO/NUS

Nonlinear and adaptive robust control of the ship course with uncertainties on the model

Manuel Casado, University of Cádiz

Robotics Vision-based System for an Underwater Pipeline and Cable Tracker
Mehdi Narimani, Isfahan University of Technology

Condition monitoring and diagnosis for subsea control systems. A subsystem prototype

Edmary Altamiranda, VetcoGray a GE Oil & Gas Business

Automated Purge Valve

Joseph Farrell, Florida Institute of Technology

Formation Stabilization of Underwater Mobile Sensing Networks
Feng Zhengping, Shanghai Jiao Tong University

Thursday, May 14 (08h30 – 10h10)

Lloyd Saal

4.5-1 Spaceborne Ocean observing - colour and radar 1

Co-Chairs: René Garello, Telecom Bretagne
Céline Danilo, Telecom Bretagne

Turbidity Measurement from ALOS Satellite Imagery

Hwee-San Lim, Universiti Sains Malaysia (USM)

Monitoring of Water Quality in the Coastal Zone Using Optical Remote Sensing

Carsten Brockmann, Brockmann Consult

Regional objective analysis for merging MERIS, MODIS/Aqua and SeaWiFS Chlorophyll-a data from 1998 to 2008 on the European Atlantic Shelf at a resolution of 1.1Km

Bertrand Saulquin, Telecom Bretagne

Technical Program

Chlorophyll Measurement from Landsat TM Imagery
Hwee-San Lim, Universiti Sains Malaysia (USM)

Thursday, May 14 (08h30 – 10h10)

Salon Bergen

10.3 Vehicle performance

Co-Chairs: Gerrit Meinecke, University of Bremen, MARUM

Update on technological developments and operational feedbacks with underwater system at Ifremer
Vincent Rigaud, IFREMER

System Verification of Autonomous Underwater Vehicles by Model Checking
Levente Molnar, University of Southampton

Interoperability of agent capabilities for autonomous knowledge acquisition and decision making in unmanned platforms
Pedro Patron, Heriot-Watt University

Modelling and Motion Simulation of an Underwater Glider with Independently Controllable Main Wings
Masakazu Arima, Osaka Prefecture University

A Survey on Aerial Submersible Vehicles
Paulo Junior, Federal University of Minas Gerais (UFMG), Brazil

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Salon Danzig

7.1-1 Imaging and vision 1

Co-Chairs: Frank Caimi

The Stereo Vision System for an Underwater Vehicle
Shojiro Ishibashi, JAMSTEC

Towards real time vision based UUV navigation using GPU technology
Jonathan Horgan, University of Limerick

Online video mosaicing through SLAM for ROVs
Fausto Ferreira, National Research Council (CNR), IEIIT

Technical Program

Online Generation of an Underwater Photo Map
Heiko Buelow, Jacobs University Bremen

3D Reconstruction Based on Underwater Video from ROV Kiel 6000 Considering Underwater Imaging Conditions
Anne Sedlazeck, Christian Albrechts University of Kiel

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Salon Franzius

2.3 Signal processing techniques

Co-Chairs: Edmund Sullivan, Prometheus Inc.
Frank Ehlers, NATO Undersea Research Centre

Superimposed chirped pulse parameter estimation based on the Extended Kalman Filter (EKF)
Jan Olivier, Council for Scientific and Industrial Research (CSIR)

System Design and Fusion Techniques for Multistatic Active Sonar
Frank Ehlers, NATO Undersea Research Centre,

Low Complexity Iterative MLSE Equalization in Highly Spread Underwater Acoustic Channels
Hermanus Myburgh, University of Pretoria

Robust matched field processing for source localization using convex optimization
Zhuan Xiao, Zhejiang University

Adaptive Model-Based Mine Detection/Localization using Noisy Laser Doppler Vibration Measurements
Edmund Sullivan, Prometheus Inc.

Thursday, May 14 (08h30 – 10h10)

Salon London

5.5 Information management

Co-Chairs: Janet Fredericks, Woods Hole Oceanographic Institution

Analysing the multidimensional wave climate with self organizing maps
Fernando Mendez, University of Cantabria

Technical Program

IMC: A Communication Protocol for Networked Vehicles and Sensors
Ricardo Martins, University of Porto, Faculty of Engineering

Integrating QA/QC Standards into OGC Sensor Web Enablement
Janet Fredericks, Woods Hole Oceanographic Institution

Playback System of Hemire ROV with Statistical Analysis on Exploration Data
Bang-Hyun Kim, Korea Ocean Research & Development Institute

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Salon Scharoun

BRE9 Maritime security and surveillance

Co-Chairs: Fritz Bekkadal, MARINTEK, Trondheim

Detection and Classification of Off Shore Artificial Objects in TerraSAR-X Images: First Outcomes of the DeMarine-DECO project
Stephane Estable, EADS Astrium

Utilization of ASAR Wave Mode Data for Shipping Safety
Xiaoming LI, German Aerospace Center (DLR)

Ship Surveillance by joint use of SAR and AIS
Susanne Lehner, German Aerospace Center (DLR)

Maritime Surveillance and Monitoring using Autonomous Vehicles with Conditional Integrator-based Control
Mernout Burger, Norwegian University of Science and Technology

Global Maritime Surveillance with Satellite-based AIS
Stephan Holsten, OHB-System AG

Thursday, May 14 (10h40 – 12h00)

Lloyd Saal

4.5-2 Spaceborne Ocean observing - colour and radar 2

Co-Chairs: René Garello, Telecom Bretagne
Sarab Tay, Telecom Bretagne

Sea surface current retrieval using ASAR WVV acquisitions
Céline Danilo, Telecom Bretagne

Technical Program

Internal Wave Observations in the Northern South China Sea from Satellite Ocean Color Imagery

Chung-Ru Ho, National Taiwan Ocean University

Analysis of chlorophyll-A concentration around the South China Sea from ocean color images

Nan-Jung Kuo, National Taiwan Ocean University

New Concept of Passive Measure using GNSS Reflected Signals in Oceanographic Applications

Sarab Tay, Telecom Bretagne

Thursday, May 14 (10h40 – 12h00)

Salon Bergen

10.6-1 Remotely operated vehicles 1

Co-Chairs: Volker Ratmeyer, University of Bremen, MARUM

Advances in developing telemanipulators for an underwater robot - REMO II
Cesar Peña Cortes, Technical Univ. of Madrid and Univ. of Pamplona

Workspace control system of underwater tele-operated manipulators on ROVs
Bong-Huan Jun, Korea Ocean Research & Development Institute

Europe's growing fleet of scientific deepwater ROVs: emerging demands for interchange, workflow enhancement and training

Volker Ratmeyer, University of Bremen, MARUM

Cable Laying ROV for Real-time Seafloor Observatory Network Construction

Katsuyoshi Kawaguchi, JAMSTEC

How to resolve the paradox of mental workload when navigating and operating underwater - Experiences on a new Human System Interface

Manfred Lueth, KOLPI S.A.S.

Thursday, May 14 (10h40 – 12h00)

Salon Danzig

7.1-2 Imaging and vision 2

Co-Chairs: Jean-Piere Hermand, Université libre de Bruxelles

Technical Program

Rotation estimation from noisy sonar images and distortion corrections for nonlinearities

Hisashi Shiba, NEC Corporation

A Bayesian Approach for Tracking Undersea Narrow Telecommunication Cables

Alberto Ortiz, University of the Balearic Islands

A new approach for Visual Underwater Mapping using Topological Shell Maps

Silvia Botelho, Fundação Universidade Federal do Rio Grande

A model-based method for reducing the sound speed induced errors in multi beam echo sounder bathymetric measurements

Mirjam Snellen, Delft University of Technology

3D Characterization of rain by means of static image processing with projected shadows

Luciano Rentería, University of Cantabria

Thursday, May 14 (10h40 – 12h00)

Salon Franzius

1.4 Acoustical Oceanography

Co-Chairs: Zbigniew Lubniewski, Gdansk University of Technology

General Oceanographic Research Vessel Radiated Noise Curve

Pam Clark, Alion Science & Technology

Using MBES backscatter strength measurements for assessing a shallow water soft sediment environment

Kerstin Siemes, Delft University of Technology

The Integrated Marine Acoustic Controller System

Edward Thurman, University of Limerick

Acoustic monitoring of the Ushant Front: a feasibility study

Olivier Carrière, Free University of Brussels (U.L.B.)

Using multibeam echoes in seafloor classification

Zbigniew Lubniewski, Gdansk University of Technology

Technical Program

Thursday, May 14 (10h40 – 12h00) Salon Scharoun

8.5 Marine safety and security

Co-Chairs: Andrea Caiti, University of Pisa, DSEA
Defu Liu, Ocean University of China

HISS: Harbour intrusion simulator system
Andrea Caiti, University of Pisa, DSEA

Prediction of Typhoon Triggered Sea Hazards in China
Defu Liu, Ocean University of China

Future Maritime Communication Technologies
Fritz Bekkadal, MARINTEK, Trondheim

A Three-Layered Architecture for Real Time Path Planning and Obstacle Avoidance for Surveillance USVs Operating in Harbour Fields
Giuseppe Casalino, University of Genoa, DIST

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Salon Bergen

10.6-2 Remotely operated vehicles 2

Co-Chairs: Volker Ratmeyer, University of Bremen, MARUM

Preliminary research on the thruster assisted crawler system for a deep-sea ROV
Tomoya Inoue, JAMSTEC

Hardware ROV Simulation Facility for the Evaluation of novel Underwater Manipulation Techniques
Leif Christensen, DFKI, Bremen

Realtime Motion Compensation for ROV-based Tele-operated Underwater Manipulators
Marc Hildebrandt, DFKI, Bremen

Design and Operational Performance of a Standalone, Passive Heave Compensation System for a Work Class ROV
Andreas Huster, OceanWorks, Canada

Technical Program

Thursday, May 14 (13h30 – 15h10)

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9.4 Marine material sciences and marine structures

Co-Chairs: Kenichi Asakawa, JAMSTEC

New Design Method of Ceramics Pressure Housings for Deep Ocean Applications

Kenichi Asakawa, JAMSTEC

An Economically Rational Selection of Submarine Hull Materials

Max Blanco, University of Southampton

Early Stage Research Vessel Design: Incorporating a Bulbous Forebody Shape to Minimize the Effects of Bubble Sweepdown

Pam Clark, Alion Science & Technology

Development of filler wire for underwater welding as a repair tool for adaptation on AUV

Yana Lizunkova, Leibniz University of Hanover

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Salon London

1.7 Ocean Noise and Seismo-Acoustics

Co-Chairs: Timothy Duda, Woods Hole Oceanographic Institution,
Olaf Boebel, Alfred Wegener Institute, Bremerhaven

Classification of Odontocete Buzz Clicks Using a Multi-Hypothesis Tracker
Odile Gerard, NATO Undersea Research Centre,

Wave Energy and Underwater Noise: State of Art and Uncertainties
Sofia Patrício, Wave Energy Centre, Lisbon

Seafloor receiver function analysis for hybrid dataset composed of both refraction survey and earthquake records

Hitoshi Mikada, Kyoto University

Geophone Calibration by means of hyperbaric chamber

Xavier Roset, Technical University of Catalonia

Student Poster Program

SYSIF a new seismic tool for near bottom very high resolution profiling in deep water

Pierre Leon, IFREMER

Breaking Wave Study from in situ Experiments

Xavier Demoulin, MAREE Lorient, France

STUDENT POSTER PROGRAM

The Student Poster Program and Competition has been an integral and important part of the OCEANS Conferences since 1989. The program is designed to foster and promote student involvement in technical societies and conferences and to provide a forum for students to interact with marine professionals.

It is open to engineering and science graduate and undergraduate students of any tertiary level university or college worldwide. The program is supported by a grant from the US Navy Office of Naval Research.

The posters will be judged by a panel of judges and prizes will be awarded at the Town Hall Reception. The posters will be on display in the Exhibition area throughout the OCEANS Conference. Students will be at their posters during breaks and free periods.

You are invited and encouraged to view the posters and talk with the students. The roster of students and poster titles are:

Backscattering of Sound from Salinity Fluctuations: Measurements off a Coastal River Estuary

Marcos Sastre, University of Massachusetts Dartmouth

Simulation of the Radar Observation of a Sea Patch using the TLM Electromagnetic Method

Thibaut Lurton, Telecom Bretagne

Control and acquisition system design for an Expandable Seafloor Observatory (OBSEA)

Marc Nogueras, Technical University of Catalonia (UPC), SARTI

Acoustic Modelling of Dolphin Sound Reception and Implications for Biosonar Design

Sabine Graf, University of Bath, Dept. of Mechanical Engineering

Student Poster Program

Fast phytoplankton classification from fluorescence spectra: comparison between PSVM and SOM

Ismael Aymerich, University of Marine Technology (UTM-CSIC)

Large Scale Optical and Acoustic Sensor Integration for Visualization

Matthew Johnson-Roberson, University of Sydney

Visual Mapping of Internal Pipe Walls using Sparse Features for Application on board Autonomous Underwater Vehicles

Adrian Bodenmann, The University of Tokyo

Blue Whale B and D Call Classification Using a Frequency Domain Based Robust Contour Extractor

Shyam Kumar Madhusudhana, San Diego State University

Analysis of acoustic modem performance for long range horizontal data transmission

Grant Pusey, Curtin University of Technology

A voice recognition system for a submarine piloting

Valentin Soulenq, ISEN, Toulon

The influence of fixed pitch angles on the hydrodynamic performance of marine cross-flow turbines

Claudio Consul, Oxford University

Sensor Network based on IEEE1451 for ocean sensors

Marcel Farré, University of Bremen, MARUM

Designing high speed monohull small crafts (HSMSC) using neural networks guided CFD based optimization

Mohamed Abdel-Salam, Alexandria University, Faculty of Engineering

Developing an IDE interface for the SNAP module

Hermann Bertram, Bremen University, MARUM

WCLES: An innovative environmental friendly combustionless engine for marine applications based on low-current electrolysis technology

Saad Sharaf, Alexandria University, Faculty of Engineering



Student Poster Program

Correction Method for Buoy Oscillation by Three GPS Receivers
Midori Shimizu, Kobe University

Using a multi-beam autonomous portable laser equipment to study optical behaviors in shallow waters
Valerie Robitaille, National Institute for Scientific Research

Forward modeling of paleo heat flow: a case study of Kristin Field, Mid-Norwegian continental shelf
Yanzhe Fu, Jacobs University Bremen

Improvement for Detection Distance of Sonar by Flat Acoustic Reflector
Yusuke Yamane, Kobe University

Offshore mussel aquaculture: new or just renewed?
Tania Lado, University of Rhode Island

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EXHIBITOR PROFILES

AANDERAA DATA INSTRUMENTS AS (AADI)

Co-Exhibitor on booth 93

Aanderaa Data Instruments AS (AADI) designs, manufactures and sells sensors, instruments and systems for measuring and monitoring in demanding environments, using state-of-the-art instrumentation that is both reliable and robust for long term observations of the marine environment. AADI with more than 40 years experience serving the industry and scientific research markets has recently developed a technology breakthrough in commercially available Remote Underwater Observation Systems. Our new Seaguard Host and an expanding line of distributed Smart Sensor technology, as well as our new AADI Real-Time Communication System, marks a turning point in distributed instrumentation for underwater and atmospheric measurements of Hydro Acoustic, Electro-Optical, Electro-Chemical, Pressure, Temperature, Meteorological data in observing networks and self-contained instrumentation. AADI is ISO 9001:2000 certified and is a trusted source for many Oceanographic Institutes, Universities, Geophysical Surveyors, Navies, Offshore Oil & Gas E&P Companies, Drilling Companies, Port & Harbour Authorities, Government Agencies, Water Authorities, and Electric Power Utilities internationally.

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ABEKING & RASMUSSEN SCHIFFS- UND YACHTWERFT GMBH & CO. KG **Booths 48, 59**

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ALFRED-WEGENER-INSTITUTE FOR POLAR AND MARINE RESEARCH **Booth LOC 81**

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- carries out polar and marine research
- contributes to the understanding of climate
- coordinates research infrastructures
- supports sustainable development

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APPLIED ACOUSTIC ENGINEERING LTD.

Booth 66

AAE is a major manufacturer of subsea acoustic navigation and positioning equipment. The product range includes the innovative USBL tracking system 'Easytrak' and a wide variety of positioning & release transponders. AAE also manufactures a marketing leading range of sub-bottom profiling products based on a component system configuration. Both the seismic energy source units, the CSP range, and the sound source products, Boomers and Sparkers, are in use throughout the world in research and commercial applications.

Email: gavinwilloughby@appliedacoustics.com

Web: www.appliedacoustics.com

AQUA VISION

Booth 64

Aqua Vision is an all-round player in the fields of hydrography and oceanography with a main focus on project management, soft- and hardware development, system integration and survey work. The combination of experienced staff and the ability to timely manage and execute projects with the in-house developed software and hardware products guarantees high-quality products and data. The company is constantly searching for technological innovations to fulfill its customer's needs. Among its customers are governmental agencies, research institutes and harbor authorities.

Email: info@aquavision.nl

Web: www.aquavision.nl

ASD SENSORTECHNIK GMBH

Booth 31

We specialise in the distribution and marketing of oceanographic instrumentation. In co-operation with our partners we develop individual solutions for our customers. Our innovative products emphasise sensor techniques, physics and analytical chemistry as well as hardware and software inputs.

We represent:

Exhibitor Profiles

ADM-Elektronik -- oceanographic instrumentation

AMT Analysenmesstechnik -- chemical sensors and expertise

Dr. Haardt Optik-Mikroelektronik -- optical instrumentation

Our exhibits include the ADM CTD-Chain and BIO-FISH, AMT O2 and H2S micro-sensors and generators and Dr. Haardt BackScat fluorometers.

Email: asd-sensors@t-online.de

Web: www.asd-sensors.com

ASL ENVIRONMENTAL SCIENCES

Co-Exhibitor on booth 75

Specialise in physical oceanography. Products include the Ice Profiler - measures ice-keel depths; Acoustic Water Column Profiler - monitors the presence and location of zooplankton, fish, or sediments; and the IRIS - data logger for Imagenex 881A Sonar. Consulting services include ice studies, flow and wave measurement and analysis.

Email: asl@aslenv.com

Web: www.aslenv.com

ATLAS ELEKTRONIK GMBH

Booths 91, 92, 102, 103

The ATLAS ELEKTRONIK Group stands for maritime and naval solutions above and below the ocean surface. The company holds a leading position in all fields of maritime high technology, from command & control systems including radio & communication systems for submarines, unmanned underwater vehicles, surface combatants and mine warfare systems and ranging to heavy-weight torpedoes, coastal protection systems and in-service support. ATLAS has established a worldwide customer portfolio. The electronics specialist is a joint company of ThyssenKrupp and EADS and has a workforce of 1800 highly skilled employees.

Email: communications@atlas-elektronik.com

Web: www.atlas-elektronik.com

AXYS TECHNOLOGIES, INC.

Booths 38, 39, 40, 49, 50, 51

Monitoring the global marine environment is becoming an increasingly important activity. AXYS Technologies, Inc. supports this effort through the design, construction and deployment of oceanographic monitoring platforms that measure a variety of parameters in water and air. In Bremen we will focus on the TRIAXYS Directional Wave Buoy with integrated Solar Panels.

Email: info@axystechnologies.com

Web: www.axystechnologies.com

bbe MOLDANEKE GMBH **Co-Exhibitor on booth 36**

bbe Moldaneke GmbH is one of the leading manufacturers of top-quality products in environmental technology. We develop and produce measuring instruments and software to assess and manage water quality in the fields of oceanography, limnology, drinking water monitoring, river dam monitoring, bathing water analysis, supervision of aqua culture systems and environmental assessment. The two core areas of our expertise are spectrofluorometers for phytoplankton analysis and algae class distinction, and real-time early warning systems, so-called toximeters, for the detection of toxins e.g. in drinking water networks.

Email: bbe@bbe-moldaenke.de

Web: www.bbe-moldaenke.de

BIG BREMEN - ECONOMIC DEVELOPMENT

Booths 47, 58

BIG Bremen - Economic Development - is the central service-providing body for business and economic development in Bremen. With our various subsidiaries - the Bremen Bank for Economic Expansion (Bremer Aufbau-Bank GmbH) and Bremer Design GmbH - we are able to offer you a complete, one-stop service package. We are the partner you need on all matters relating to business and regional development. Our investment services are: International network, Inward investment as well as How to set up a company.

Email: mail@big-bremen.com

Web: www.big-bremen.com

BIS - BREMERHAVEN ECONOMIC DEVELOPMENT COMPANY.

Booths 113, 114, 115

The Economic Development Company (BIS) is the central point of contact for all matters relating to business development in Bremerhaven.

We offer you:

- Research and Development area for maritime economy and maritime sciences
- Information and assistance for your investment project
- Customised industrial areas and properties
- Support for investment, technology and start-ups, as well as many other support programmes
- Direct contacts to the business and research communities, politicians and government authorities in the State of Bremen

Email: wirtschaft@bis-bremerhaven.de

Web: www.bis-bremerhaven.de

BLUEFIN

Co-Exhibitor on booth 44

Autonomous Underwater Vehicle (AUV) / Glider

Email: info@bluefinrobotics.com

Web: www.bluefinrobotics.com

BMTI - ALCEN GROUP

Booths 67, 68

The French company BMTI has been designing, developing and creating product ranges and parts made from composite materials and syntactic foam, for use in oceanography, offshore. These are industry suitable for depth ratings ranging from 1,000 to 8,000 metres :

- syntactic foam standard blocks offering a low-cost solution for adapting to the buoyancy constraints
- buoyancy solutions for oceanographic operations : modular, low drag buoys, cylinders

Email: contact@bmti.fr

Web: www.bmti.fr

BREMERHAVEN UNIVERSITY OF APPLIED SCIENCES

Booth LOC 70

Bremerhaven University is a university of applied sciences. Thus particular value is placed on as great a practical focus as possible. Apart from practical work in modern laboratories, professional practical experience is guaranteed through work on applied research and development projects within the University. The links between Bremerhaven University of Applied Sciences and the business community are very close. More than 2,600 students are currently registered at the Bremerhaven University, which offers 17 degree study courses. The spectrum includes the natural and engineering sciences as well as economics.

Water is becoming one of the economic sectors of the future. That is why Bremerhaven University – in cooperation with the Alfred Wegener Institute of Polar and Marine Research – has developed the Maritime Technologies course. The course unites the competence of Bremerhaven University in the field of seafaring, which has evolved over more than 100 years, with new modern technologies and the demands of the maritime sector. Further study courses in Windenergy and Biotechnology (including Marine Ressources) are offered and several institutes are engaged in marine research projects, ensuring that the contents of the courses are always up to date.

Email: ozielinski@hs-bremerhaven.de

Web: www.hs-bremerhaven.de

BREST METROPOLE OCEANE - FRANCE / SEA TECH WEEK 2010

Booth 74

Brest, large and strategic atlantic port, and leading port for the repair of the naval fleets and commercial vessels is the focus for almost half of french research capability in the field of marine sciences.

Brest metropole oceane organize the 7th Sea Tech Week conference, international marine science and technology week, from 21 to 25 june 2010, in Brest. The conference hosts workshops and seminars run by scientific organisations and societies and also a professional exhibit.

Sea Tech Week is supported by IEEE/OES within a partnership with Oceans Conferences held in Europe.

Email: seatechweek@brest-metropole-oceane.fr

Web: www.seatechweek-brest.org

BRIESE SCHIFFAHRTS GMBH & Co. KG

Abteilung Forschungsschifffahrt

Booths 54, 55

Since January 1, 2004 the research vessel department at Briese Schifffahrts GmbH & Co. KG is responsible for the management of the mid-sized, German research vessels. As part of a worldwide operating shipping company the research department additionally offers chartering and brokerage of special purpose vessels, the selection and recruitment of duly qualified and experienced crew, an interface for partners from shipping and science as well as the design, creation and realization of logistic models.

Email: research@briese.de

Web: www.briese.de

CENTRE OF MARITIME RESEARCH IN ELSFLETH

Booth 42

The Centre of Maritime Research in Elsfleth serves as a platform for applied research in the field of shipping and ocean technology. Its purpose is to initiate and oversee projects which are conducted in conjunction with maritime institutes, universities, shipyards, shipping lines and private enterprise. The collaboration of science and business highlights the great significance of applied research and guarantees the swift transfer of science and technology to everyday practice.

The Centre of Maritime Research has been created through a public-private partnership between the University of Applied Sciences Oldenburg / Ostfriesland / Wilhelmshaven (FH OOW) and Beluga Shipping GmbH.

Email: info@maritimes-forschungszentrum.de

Web: www.maritimes-forschungszentrum.de

CONTROS SYSTEMS & SOLUTIONS GMBH

Booth 45

CONTROS Systems & Solutions GmbH develops, produces and markets underwater sensor systems to detect hydrocarbons, Methane, CO₂, Mono Ethylene Glycol, Fluorescence Dye and oil in water up to a water depth of 6,000m in any condition and in combination with data logging solutions. The product portfolio has successfully been expanded to include subsea power supplies and battery systems to be used for autonomous subsea applications as well as AUV's.

Email: d.esser@contros.eu

Web: www.contros.eu

CPU, Dr. Christian Proeber Unterwassertechnik

Booth 77

Sales and Marketing Office for underwater equipment and technology, based in Bremen.

Representation of foreign manufacturers of such equipment in German speaking countries Germany, Austria and Switzerland.

Products are TV and lighting, Hydroacoustics, ROV/AUV, Sensors, Connectors and Floatation Materials.

Email: cpu-bremen@t-online.de

Web: www.cpu-bremen.de

CSnet™

Co-Exhibitor on booth 45

CSnet™ introduces a Modular Seafloor Communications Network providing global users with a pre-engineered, expandable system that can be deployed (and redeployed) anywhere in water.

CSnet's Offshore Communications Backbone (OCB) consists of a network of power and fiber optic cables and sensor ports connected to a surface communications buoy. The OceanNET™ buoy, was designed and built by Maritime Communication Services MCS, a subsidiary of Harris Corp. and serves as the command control and data backhaul for the OCB.

Email: info@csnetintl.com

Web: www.csnetintl.com

DEVELOLOGIC GMBH

Booth 86

From Seafloor to Desktop: develogic specializes in the design and manufacturing of technology leading solutions for integrated sub sea communication. Our product range includes the hydro acoustic modem HAM.NODE with cutting-

edge signal processing technology, the HAM.RCOM remote satellite/RF communication module, releaser units, advanced pressure housings, as well as customer specific software and hardware.

Email: info@develgoic.de

Web: www.develgoic.de

DMKN, The German Maritime Competence Net Co-Exhibitor on booth 14

The DMKN (Deutsches Maritimes Kompetenz Netz) has been established in 2003 by the German Naval Institute DMI (Deutsches Marine Institut) satisfying the need for a modern internet representation in order to reach the entire maritime community. This concept took into special consideration the wide range of interests. Navy, Armaments, Shipbuilding, Marine Technology and Maritime Economy can profit considerably from this common platform that allows for a cross-referencing research in five Competence Centres which form the basic electronic marketplace and also facilitate an interactive dialogue between interested users and pertinent scientific, industrial, institutional and governmental experts:

- Shipbuilding and Technology
- Navy and Armaments
- Marine Technology and
- Maritime Economy
- Maritime Security

In this respect the DMKN forms an ideal basis for a successful internet representation for companies and scientific and/or governmental institutes. This globally and freely accessible internet platform can also be used to enhance the professional visibility of every participating partner remarkably by obtaining special sponsor privileges according to the actual service catalogue that can be obtained from our representatives at the DMKN exhibition site.

Email: timmm@dmkn.de

Web: www.dmkn.de

DVV-MEDIA GROUP GMBH, Schiff & Hafen / Ship & Port Co-Exhibitor on booth 14

The monthly trade magazine for shipbuilding, shipping and maritime engineering Schiff & Hafen as well as the English-language quarterly published "Ship&Port" represent high expertise analyses trends from all areas of the maritime sector, concentrating on shipbuilding, marine and offshore technology. Specialists of all parts of the maritime branch are kept up-to-date regarding the entire range of modern shipbuilding technology, the latest innovations concerning shipbuilding and offshore equipment and systems as well as naval

shipbuilding engineering and shipping management.

Email: silke.sadowski@dvvmedia.com

Web: www.schiffundhafen.de

EDGE TECH

Co-Exhibitor on booth 44

Side Scan Sonar Systems, Subbottom Profiling Systems

Email: info@edgetech.com

Web: www.edgetech.com

EIVA A/S

Booths 38, 39, 40, 49, 50, 51

EIVA is a unique provider of software, hardware and integrated system solutions for marine surveying, environmental- and oceanographic monitoring.

Software comprises modules for integrated navigation, sonar data acquisition, survey data editing, digital terrain modeling and fair-sheet charting. Hardware includes ScanFish family of intelligent undulating vehicles. EIVA also provides equipment rental. In Bremen we will focus on the ScanFish systems which can be used with many different sensor configurations.

Email: info@eiva.dk

Web: www.eiva.dk

EVOLOGICS GMBH

Booth 78

EvoLogics presents the R-Series of subsea modems with advanced spread-spectrum underwater communications technology providing reliability in adverse conditions and high speed full duplex communication. Superior multi-channel data management, built-in networking, tracking and positioning functions and USBL allow easy integration and low ownership cost. We also have innovative biomimetic concepts for AUVs.

Email: info@evologics.de

Web: www.evologics.de

FALMAT

Co-Exhibitor on booth 44

Custom Cable technologies for global applications

Falmat is a leading manufacturer of specialty cables for all sub sea applications. Our new Deep Rated Ethernet Cables will be featured at the Oceans Europe Conference. Falmat has appointed IGP as its exclusive sales representative agency in Germany. Please stop by IGP's stand to learn more about Falmat's manufacturing capabilities and products.

Email: sales@falmat.com

Web: www.falmat.com

FIELAX, Gesellschaft für wissenschaftliche Datenverarbeitung mbH

Booth 24

FIELAX offers scientific-technical services for research and shipping. One of our main tasks is the installation, operation and maintenance of research platforms, measuring devices and data acquisition systems, mainly in the marine environment.

FIELAX plans and operates marine surveys. We offer Heat Flow Probes and Temperature Gradient Probe, either for rent or purchase.

FIELAX performs technical and scientific support for station work including the deployment of ROVs (with own certified ROV pilots) and the maintenance of ROV systems on and offshore. Postprocessing and further visualisation of video and navigation data is offered, too.

Our clients are major research institutes, universities, operators of research vessels, offshore planners and the oil exploration industry. Our highly qualified team of scientists and engineers has long-standing experience in surveying operations on land and at sea.

Email: info@fielax.de

Web: www.fielax.de

FLOTATION TECHNOLOGIES, INC.

Booths 38, 39, 40, 49, 50, 51

Flotation Technologies is a world leader in the design, engineering and manufacturing of deepwater buoyancy systems and serves the offshore oil, oceanographic, seismic and government markets. With customers in more than 40 countries, the company prides itself on delivering superior quality marine solutions. In Bremen we will focus on the products for the oceanographic market like ADCP buoys for moorings.

Email: info@flotec.com

Web: www.flotec.com

FUGRO OSAE GMBH

Booths 26, 37

FUGRO OSAE GmbH was established in 1983 under the name OSAE Offshore Survey and Engineering, Gesellschaft für Seevermessung mbH. With an excellent reputation both in and outside of Germany as one of the major, internationally-operating survey companies in the field of marine surveying, the company was acquired in October 2006 by Fugro, a worldwide company operating at sea, on land and by air. Specialising in all types of hydrographic

surveys, the majority of FUGRO OSAE's work is in the non Oil & Gas sector although exceptions are numerous. A particular specialty is in cable and pipeline route and inspection surveys with a wide range of practical experience throughout the world. FUGRO OSAE owns and operates a fleet of survey vessels differing in both size and instrumentation, thus offering the rapid execution of services over the whole spectrum from inland waterways to deep water ocean surveys.

Email: info@fosae.de

Web: www.fosae.de

GEOACOUSTICS - A KONSBERG COMPANY

Co-Exhibitor on booths 52, 53

GeoAcoustics is a leading manufacturer of sonar survey equipment. Our products are manufactured in the UK and are available through GeoAcoustics and Kongsberg Maritime sales offices as well as independent sales representatives worldwide.

Email: sales@geoacoustics.com

Web: www.km.kongsberg.com/geoacoustics

GERMAN MARINE RESEARCH CONSORTIUM (KDM)

Booth 117

German Marine Research Consortium - KDM - is made up of fourteen institutions and universities of Germany in the field of marine and polar sciences as well as of coastal research. The members are part of a European and global network of such institutions. With approximately 2,200 scientists of basic and applied marine research, KDM provides comprehensive expertise to meet global challenges having to do with the sea and our environment.

The major objectives of KDM are

- advancement of science and research, in particular in the field marine sciences including polar and coastal research,
- fostering the collaboration of its member institutions and the development of joint research programmes,
- intensifying the cooperation within German, European and international marine research and the use of infrastructure and large equipment
- joint public relations addressing decision makers in Germany and the European Union

Email: peinert@deutsche-meeresforschung.de

Web: www.deutsche-meeresforschung.de

GKSS RESEARCH CENTRE GEESTHACHT

Booths 19, 20

The Institute for Coastal Research of the GKSS Research Centre Geesthacht is conducting research on coastal and adjacent shallow sea areas within the current programme "Polar Regions and Coasts in the Changing Earth System/PACES". The research specifically aims at establishing a rational scientific basis for the management of coastal zones and on the coastal response to global climate change. One scope of GKSS coastal research has led to the COSYNA-Project (Coastal Observation System for Northern and Arctic Seas). The principal goal of this project is the construction of a long-term observatory for the German part of the North Sea.

Email: contact@gkss.de

Web: www.gkss.de

GMT - GERMAN ASSOCIATION FOR MARINE TECHNOLOGY

Booth 14

The GMT (German Association for Marine Technology) was founded in 1983 and represents at present around 100 companies and research institutions towards the public, political and governmental bodies.

The German Association for Marine Technology covers the following maritime topics: Aquaculture / Mariculture Technology, Coastal Zone Management, Gas Hydrate and Ocean Mining Technology, Hydrography, Marine Research Technology, Maritime Safety and Security, Marine Environmental Protection, Offshore Technology – Oil & Gas and Offshore Wind Energy, Polar Technology, and Underwater and Deep Sea Technology.

GMT provides the interface between Marine Science and Research and Industrial Applications in order to initiate, support and co-ordinate national and international R&D projects.

GMT also supports member companies in marketing and in finding industrial and/or research partners. GMT is organising meetings of their members with Federal and State Parliamentarians in order to keep the politicians informed about world wide developments in Marine Technology in order to increase the acceptance of Marine Technologies and being supported for their own developments of innovative technologies.

Finally, GMT organises the participation of GMT members at national and international fairs at GMT Community booths.

Email: gmt@maritime-technik.de

Web: www.maritime-technik.de

HELZEL MESSTECHNIK GMBH

Booth 75

HELZEL is the TÜV certified manufacturer of the well known remote ocean sensing system WERA. The shore-based WERA provides reliable data of ocean surface currents and significant wave height and direction over long distances (> 200 km) with outstanding spatial and temporal resolution for VTS, SAR and environmental protection applications.

Email: wera@helzel.com

Web: www.helzel.com

HEMISPHERE

Co-Exhibitor on booth 44

DGPS-Receiver, DGPS OEM Boards, Beacon Receiver Boards, Antenna Products

Email: info@hemispheregps.com

Web: www.hemispheregps.com

hhp GMBH

Booths 33, 34

The company hhp has many years of experience in the development and distribution of medical products and is the leading supplier of tested medical devices in the field of massage technique. Tens of thousands of satisfied customers worldwide benefit from the fact that the production takes place exclusively in Germany - this ensures the highest possible quality according to the German Medical Devices Act.

Email: info@hhp.de

Web: www.hhp.de

hs ENGINEERS

Co-Exhibitor on booth 31

HS Engineers (Engineering Bureau Dr.-Ing. Helmut Schlueter VDI) offers development, delivery and service of special measuring equipment. Core products are inductive or electro-magnetic (EM) current sensors. These are used in pure current meters, in directional wave probes, and in multi-parameter-probes as direct reading instruments as well as autonomous memory probes. We present the proven current meters and directional wave probes ISM-2000 and ISM-2000M respectively (developed with MesSen Nord GmbH) and our latest product line - the multi-parameter-probes Series 2001. Within this portfolio of instruments is the successful analogue current sensor ISM-2001 which easily integrates into much different current sensing applications, even into compact solutions for mobile field measurements with wireless data transfer.

Exhibitor Profiles

Email: info@hs-engineers.de

Web: www.hs-engineers.de

IEEE / OCEANIC ENGINEERING SOCIETY

Booth 17

The Oceanic Engineering Society (OES) of the Institute of Electrical and Electronics Engineers, Inc. (IEEE) seeks to advance the science and technology of Ocean Engineering. Its objectives are scientific, literary, and educational in character. The Society strives for the advancement of the theory and practice of electrotechnology applied to the ocean environment not only by ocean engineers but also by individuals in allied branches of engineering and related arts and sciences. The Society maintains a high level of professional standards among its members and affiliates and through them promotes technical excellence and actively encourages the exchange of information through conferences, meetings, workshops and publications. Stop by the IEEE/OES booth for membership information.

Email: elcreed@ieee.org

Web: www.ieeeoes.org

IFREMER

Booths 16, 27

As the French research institute for exploitation of the sea, Ifremer contributes, through studies and expert assessments, to knowledge about the ocean and its resources, monitoring of marine and coastal zones and the sustainable development of maritime activities. To these ends, it designs and operates observational, experimental and monitoring tools and facilities. Ifremer manages the French ocean research fleet and oceanographic databases on behalf of the entire scientific community.

Email: infosc@ifremer.fr

Web: www.ifremer.fr

IGP, Ing.-Büro G. Pinnow

Booth 44

The company IGP was founded in 1981. Our activities are in

- Consulting
- Sales
- Leasing

We are specialized in

- Oceanographic
- Underwater Measuring Instruments
- Polar and Marine Environmental Research in the oceanographic

market for underwater instruments and navigation systems.

We consult our customers with the selection of the right instruments (tools) and we also offer After Sales Service from our principals as well as the professional repair and calibration of the instruments. We offer for example products like

- CTD systems, Releaser, Transponder, Pinger and Modems
- ROV, Side Scan Sonar, Echosounder, Bathymetry Systems
- Fluorometer, Transmissometer, Absorptionsmeter
- GPS/DGPS, Underwater Inspection Survey Systems

Email: igp@igp.de

Web: www.igp.de

IMAGENEX TECHNOLOGY CORP.

Co-Exhibitor on booths 38, 39, 40, 49, 50, 51

Imagenex is building small high resolution sonars. With continuous technological advancements, software and hardware compatibility, portability and overall ease of use, Imagenex sonar systems set the industry standard as the most specified sonar systems worldwide. In Bremen we will show a small SideScan Sonar and Multibeam system.

Email: info@shaw.ca

Web: www.imagenex.com

imare INSTITUT FÜR MARINE RESSOURCEN GMBH

Co-Exhibitor on booths 113, 114, 115

An interdisciplinary team of experts in Marine Physics and Sensors, Aquaculture, Cell and Molecular Biology, Marine Bionics and Blue Bioindustries is open to find new solutions in marine economic and scientific sectors. We offer a portfolio of research assignments for our customers, custom-designed technical business consulting and product development. IMARE by being supported by the European Regional Development Fund (EFRE) stands for solutions in collaboration with academia, industry, and public administration.

Email: info@imare.de

Web: www.imare.de

INNOMAR TECHNOLOGIE GMBH

Booth 32

Innomar Technologie GmbH develops and produces efficient acoustic underwater systems for more than 10 years. The main product line is the SES-2000 series of parametric sub-bottom profilers with echo-sounder functionality for shallow (0.5m to 500m) and deep water (up to full ocean depth). Parametric sound generation guarantees an outstanding horizontal and layer resolution

Exhibitor Profiles

due to transmission of short focused sound pulses at high ping rates (up to 50pps).

The narrow-beam SES-2000 sub-bottom profilers are perfectly suited for exploring the sub-seafloor at high resolution with a sediment penetration of up to 150m. Applications include the detection of fluid mud layers and sediment structures for dredging and geological surveys as well as searching embedded objects like pipelines or archaeological artefacts.

Email: info@innomar.com

Web: www.innomar.com

INTERNATIONAL OCEAN SYSTEMS

Booth 6

International Ocean Systems is a European-based Diver Group magazine with a bi-monthly circulation in excess of 10,000 worldwide. It serves the commercial oceanography market covering the fields of ocean data gathering, underwater surveying, and instrumentation. Readers are predominantly upper management, designers/engineers and scientists.

Email: astrid@divermag.co.uk

Web: www.intoceansys.co.uk

iSITEC GmbH

Co-Exhibitor on booths 113, 114, 115

iSITEC offers scientific-technical products and services in the field of environmental and marine technologies.

This includes the development and manufacturing of customized devices for measurement-, analysis- and sampling applications and the programming of data acquisition and data visualisation software.

In addition a competent service for technical devices and facilities is offered.

Thomas Hanken

Email: thanken@isitec.de, mail@isitec.de

Web: www.isitec.de

IXSEA

Co-Exhibitor on Booth 44

Underwater Acoustics, Oceanographic Instrumentation, USBL Navigation Systems

Email: info@ixsea.com

Web: www.ixsea.com

JACOBS UNIVERSITY GMBH

Booth 41

Jacobs University Bremen is a private, independent research university founded in 1999. Two schools (Science and Engineering, Humanities and Social Sciences) as well as a Centre for Lifelong Learning provide undergraduate and graduate programs in a total of 25 different areas. Currently 800 students coming from 91 different countries, and about 250 graduate students study on Campus. The faculty of Earth Science and Engineering at Jacobs University (currently 65 professors) is developing a geoscience research centre with the intention to strengthen electronic management of geoscience data, the numerical simulation of geological processes and to build up a new facility of internet controlled oceanography.

Email: l.thomsen@jacobs-university.de

Web: www.jacobs-university.de

JASCO APPLIED SCIENCES

Booth 89

Jasco Applied Sciences offer a specialised marine acoustic monitoring and environmental impact assessment service for all industrial operations using wide-area robust, long-term recording sensors and a state-of-the-art acoustic processing suite to extract ambient, shipping and industrial noise as well as marine mammal vocalisations to support population studies for damage mitigation requirements. Jasco's world-wide capability has been successfully deployed in all ocean settings from warm water to extreme Arctic environments, under a rigorous, industry-standard health and safety culture, to provide a world-class maritime scientific support service to a range of international clients.

Email: europe@jasco.com

Email: robin.burns@jasco.com

Web: www.jasco.com

J. BORNHÖFT INDUSTRIEGERÄTE GMBH

Booths 38, 39, 40, 49, 50, 51

J. Bornhöft is representing leading manufacturers of oceanographic equipment for over 30 years. Based on this experience, we not only offer system components like ADCP's, CTD's, AUV's, Glider, ROV's etc., but are also your competent partner for turnkey solutions. In Bremen you will find a wide selection of new instruments which we present with our partners in the oceanographic industry.

Email: info@bornhoeft.de

Web: www.bornhoeft.de

JFE ALEC

Co-Exhibitor on booth 44

CTD Equipment, Salinity Sensors, Current Speed/Current Direction, Turbidity Sensors, DO- and PH-Sensors

Email: info@jfe-alec.co.jp

Web: www.jfe-alec.co.jp

KONGSBERG MARITIME

Booths 52, 53

Kongsberg Maritime is a global source for marine and offshore electronics. We are present with R&D, manufacturing facilities and offices in 25 countries worldwide. Kongsberg Maritime provides innovative and reliable solutions for shipping, offshore, subsea, navy and fisheries, ship and fleet management, maritime training, port and harbour surveillance and more. Along with our 'Oil & Gas' and 'Offshore & Merchant Marine' Division we have a Subsea Division, which operates in the product areas underwater positioning and communication, hydrography and shallow seismic, sonars for the offshore and the defence markets, camera systems, fisheries and fisheries research (Simrad), as well as autonomous underwater vehicles.

Email: km.hamburg@kongsberg.com

Web: www.kongsberg.com

L-3 ELAC NAUTIC

Booths 65, 76

With more than 80 years of experience, L-3 ELAC Nautik (Kiel, Germany) enjoys a worldwide reputation for the innovative development and manufacture of underwater acoustic systems and components. Customized solutions and leading-edge technology characterize our wide range of products covering sonar sensors and systems, digital and analogue underwater communication systems and echo sounders for military, survey and commercial purposes.

Email: elac.marketing@L-3com.com

Web: www.elac-nautik.com

L-3 MARIPRO

Co-Exhibitor on booths 65, 76

L-3 MariPro (near Santa Barbara, California) specializes in providing sub-sea cabled sensor system solutions. We are a system concept through marine operations company offering turnkey solutions to loyal customers spanning the globe. With nearly 5 decades of corporate experience, we have developed, built and installed more than 60 systems comprised of nearly 300 sensor strings in excess of 7,000 kilometers of cable at ocean depths ranging from 20

to 5,000 meters. L-3 MariPro is applying these core corporate strengths to the emerging cabled ocean observing market by participating in programs such as MARS, NEPTUNE, ESONET and others.

Email: maripro.info@L-3com.com

Web: www.L-3com.com/maripro

LYYN AB

Co-Exhibitor on booth 45

Our technology is called LYYN™ Visibility Enhancement Technology (V.E.T.). Visibility is enhanced (particularly the possibility to see colors, movement and contours) in subsea, fog, snow, dust, sand, lowlight, etc as well as in e.g. medicinal applications. V.E.T. works on images and videos from normal color cameras, but can also be used in processing saved material. As LYYN™ V.E.T. can be integrated into existing systems as a “turbo charger”, no expensive upgrade of complete systems is required.

Email: info@lyyn.com

Web: www.lyyn.com

MACARTNEY A/S

Co-Exhibitor on booths 62, 63

MacArtney A/S is a global supplier of underwater technology specialising in design, manufacture, sales and service of a wide range of systems to offshore operators, surveyors, the renewable energy sector, ocean sciences, security forces and navies across the world.

We offer a range of advanced and reliable systems from proven components, cables and connectors, to state-of-the-art integrated packages, including fibre optic telemetry systems and remotely operated towed vehicle systems. All the products we supply are designed and tested to supply high quality reliable performance in the challenging underwater environment.

MacArtney A/S is a privately owned corporation with group headquarters in Esbjerg on the West Coast of Denmark. From our head office in Denmark, we have been providing logistical, technical, financial and marketing support to all of the companies within the group since 1978.

Email: info@macartney.com

Web: www.macartney.com

MARUM

Booth LOC 69

MARUM is a cooperative facility at the University of Bremen offering a number of technical and scientific services and developing innovative technology in support for scientific operations. With the deep sea ROV system MARUM-

QUEST (ALSTHOM-Schilling) with a maximum deployment depth of 4000 m over 200 dives have been carried out. The operations are part of scientific missions where the goal is to survey the region of interest and to deploy and recover deep-sea instruments. A deep diving AUV (5000 m) equipped with high resolution sonar mapping systems has recently been acquired and is complementing the operation of the deep sea ROV system MARUM-QUEST. One of the permanent tasks of MARUM lies in the maintenance of the scientific information system PANGAEA (Network for Geological and Environmental Data – www.pangaea.de), which is a system for acquisition, processing, long term storage, and publication of geo-referenced data related to earth science fields.

Email: waldmann@marum.de

Web: www.marum.de

MAX PLANCK INSTITUTE FOR MARINE MICROBIOLOGY

Booth LOC 80

At the Max Planck Institute for Marine Microbiology, microbiologists, molecular biologists and biogeochemists work together to understand basic principles of marine microbial ecology. Our focus is on the anaerobic (oxygen-free) world below the sediment surface, because this is where many interesting and hitherto unknown life forms exist that play a crucial role for the coupling of element cycles – and hence for the chemistry of the oceans. The researchers at the institute cover a broad range of disciplines and areas of expertise, from micro-sensors to microbiology, from geochemistry to genome analysis, and from molecular ecology to mathematical modelling.

Email: mschloes@mpi-bremen.de

Web: www.mpi-bremen.de

MBT GmbH

Booths 62, 63

MBT GmbH is a sales and engineering company for marine and underwater technology. Since October 2000 we have been a member of the MacArtney Group, a worldwide leading network of companies specialized in the supply and service of underwater technology products and systems.

MBT GmbH concentrates its expertise on the sale of oceanographic and hydrographic instrumentation. In addition MBT GmbH offers a large range of services e.g. installation of instruments and integration of components on existing platforms as well as design of monitoring networks and system concepts including software.

Since 2006 MBT GmbH operates a fully equipped calibration and service laboratory for oceanographic instrumentation. This is the only manufacturer

independent facility of this type in Germany. We are also offering mil standard service under supervision of the German Navy Quality Assurance.

MBT GmbH is the competent partner for all those who wish to take samples and measure in oceans, rivers, lakes and harbours.

Email: info@m-b-t.com

Web: www.m-b-t.com

McLANE RESEARCH LABORATORIES, INC.

Co-Exhibitor on booths 38, 39, 40, 49, 50, 51

McLane provides advanced time series samplers and engineering design services to the international oceanographic community. Our established product line includes a range of bio-geochemical sampling instruments for use in oceanographic research. The McLane Moored Profiler autonomously profiles the water column along a fixed tether while carrying a selection of sensors including a Sea-Bird CTD, current meter and other optional sensors.

Email: info@mclanelabs.com

Web: www.mclanelabs.com

MTS, MARINE TECHNOLOGY SOCIETY

Booth 18

Email: chris.barrett@mtsociety.org

Web: www.mtsociety.org

MYRIAX PTY LTD

Co-Exhibitor on booth 45

Myriax Pty Ltd is a group of high-tech R&D companies with offices in Australia, USA and Japan. We develop high quality hardware and software products to meet real world environmental management needs.

Our Mission is to enhance the sustainability and quality of life through the delivery of valuable and innovative technologies to the world.

Email: info@myriax.com

Web: www.myriax.com, www.eonfusion.com, www.echoview.com

NAUTILUS MARINE SERVICE GMBH

Booth 93

NAUTILUS MARINE SERVICE GmbH was founded in 1986; the company is registered in Bremen, Germany. NAUTILUS is a subsidiary company of RF Forschungsschiffahrt GmbH, Bremen.

The objective is to offer equipment sales, technical consultancy, operator's assistance, repair and maintenance services to the marine sciences community, offshore industry and armed forces. Our line of equipment includes

Exhibitor Profiles

- VITROVEX® glass floatation spheres and instrument housings
- Ocean Bottom Seismometer Systems, PMD sensors and recorders
- Sonar systems,
- Oceanographic instruments,
- Satellite telemetry,
- Underwater TV, cameras and lighting,
- Towed sensor platforms,
- Cables, ropes, mooring components and underwater connectors.

We represent a number of renowned manufacturers in this field of marine technology in Germany.

Email: info@nautilus-gmbh.com

Web: www.nautilus-gmbh.de

NAVAL UNDERSEA WARFARE CENTER

Booth 30

The Naval Undersea Warfare Center (NUWC) is the U.S. Navy's full-spectrum research, development, test and evaluation, engineering and fleet support center for submarines, autonomous underwater systems, and offensive and defensive weapons systems associated with undersea warfare. NUWC is under the command of the Naval Sea Systems Command (NAVSEA).

NUWC scientific and engineering staff offer expertise in science and technology; technical direction; and system design, development, test and evaluation. NUWC is on the forefront of the development and maintenance of scientific facilities for underwater research, which supports numerous Navy programs. NUWC has been responsible for the development of nearly all submarine combat systems, underwater acoustic sensors and weapons systems operating in the U.S. Fleet today. Working closely with the Fleet, NUWC scientists and engineers meet current and future operational requirements and solve technical problems.

Email: gregory.b.jones1@navy.mil

Web: www.nuwc.navy.mil

NORDDEUTSCHE SEEKABELWERKE GMBH

Booth 56

Norddeutsche Seekabelwerke (NSW) was founded in 1899 by Felten & Guillaume and Deutsch-Atlantischen Telegraphengesellschaft. As pioneers in sea cable technology, it was already in 1904 that NSW produced its first gutta-percha insulated major undersea telecommunication cable and installed it across the distance of 7,993 kilometres from Borkum via the Azores to New York. Over the years, NSW has become one of the world's leading companies in the field of power and telecommunication sea cables, air cables, special

cables for the offshore industry and as supplier for intelligent plastic products. From its headquarters in Nordenham and various international sales offices, the company advises and supports its customer base spread out all over the world. NSW is part of the General Cable Group which generated in 2007 a turnover of 6 billion US dollars with a workforce of more than 12,000 employees.

Email: info@nsw.com

Web: www.nsw.com

NORTHWEST-VERBUND MEERESFORSCHUNG e.V.

Booths LOC 69, 70, 80, 81

The Marine Research Association NWVM was founded by members of marine research institutions in the north western region of Germany, encompassing the Federal States of Bremen and Lower Saxony. This registered association aims at performing joint research projects and developing transfer projects with the business sector. In short the Association serves as competent contact point for interested companies for all questions regarding marine technologies and marine research. It creates synergies and collaborations within the German Northwest and provides a platform for co-ordination and planning of joint oceanographic research. It offers know how in the areas of marine climate and applied marine research in coastal, deep sea and polar settings, as well as expertise in environmental genomics.

Email: mschulz@uni-bremen.de

Email: jwesnigk@h-w-k.de

Web: www.nwv-meeresforschung.de

NORTEK AS, terra4 GmbH

Booth 116

Nortek AS is a scientific instrumentation company that develops and distributes instruments for water velocity and wave measurements. Continuously striving to improve their performance, they have a number of technological 'firsts' due to a strong development team. The first rate production system assures to receive quality products on time. All Nortek products are based on the acoustic Doppler principle and they span from single point turbulence sensors to long range current profilers, to combined wave height and direction, as well as current profile sensors. The customers are scientists, research institutions, and consulting engineers, all with demanding applications requiring state-of-the-art instrumentation that is both reliable and easy to use.

The team of terra4 - Gesellschaft für Geosystemanalyse mbH analyses aquatic systems and catchment areas and carries out landscape investigations. In Germany terra4 GmbH is a representative of Nortek AS.

Exhibitor Profiles

Email: carsten.wirtz@terra4.de, inquiry@nortek.no

Web: www.nortek-as.com, www.terra4.de

NURC, NATO RESEARCH CENTRE

Booth 57

One of three research and technology organisations in NATO, NURC conducts research in support of NATO's operational and transformation requirements. Our focus is on the undersea domain and on solutions to maritime security problems. NURC maintains a strong reputation for bringing the best and brightest researchers together through rotational scientific staffing and through extensive partnering with NATO member nations.

Email: pao@nurc.nato.int

Web: www.nurc.nato.int

OCEANOLOGY INTERNATIONAL

Booth 5

Oceanology International is the global forum where industry, academia and government share knowledge and connect with marine technology and ocean science, improving their strategies for measuring, exploiting, protecting and operating in the world's oceans.

9th – 11th March 2010, London Excel

Email: oiteam@reedexpo.co.uk

Web: www.oceanologyinternational.com

OCEANSCAN- MARINE SYSTEMS & TECHNOLOGY

Booth 9

OceanScan - Marine Systems & Technology is a spin-off from Porto University in Portugal, one of the leading institutions in underwater robotics in Europe.

OceanScan-MST is pioneering a low cost approach to oceanographic surveys based on its flagship product, the LAUV. OceanScan-MST delivers innovative surveying services and advanced engineering services for ocean systems.

Email: info@oceanscan-mst.com

Web: www.oceanscan-mst.com

OCEANSCIENCE Group

Co-Exhibitor on booths 38, 39, 40, 49, 50, 51

The OceanScience Group is a world leader in the development and manufacture of oceanographic and hydrologic field equipment and instrumentation. Our products include a wide range of autonomous, RC and tethered boats, the Underway CTD, bottom platforms, weather stations and communication packages. In Bremen we will focus on the Underway CTD, a portable system

Exhibitor Profiles

providing cost-effective, accurate profiles of temperature and salinity (Sea-Bird CTD) from underway vessels.

Email: info@oceanscience.com

Web: www.oceanscience.com

OPTIMARE

Booth 79

With sophisticated technologies from research and development to product and service, OPTIMARE develops and sells sensors, remote sensing systems and data acquisition/network solutions for environmental monitoring and marine and polar research. As platforms, the company serves aircraft and ships as well as land- and underwater-operated systems.

Email: info@optimare.de

Web: www.optimare.de

ORE OFFSHORE

Co-Exhibitor on booths 38, 39, 40, 49, 50, 51

For 40 years, ORE Offshore has been a leading manufacturer of high accuracy acoustic positioning systems for use within the offshore, military and institutional markets. These systems are used to track underwater vehicles including ROV's, AUV's and Towed Instrumentation Packages. The heart of these products is the Track Point Ultra Short Baseline (USBL) deck unit. In Bremen, we will show the new Broadband Acoustic Tracking System BATS. By utilizing broadband technology, ORE is able to achieve approximately double the effective range of traditional Trackpoint systems.

Email: info@ore.com

Web: www.ore.com

PRO-OCEANUS SYSTEMS INC.

Booth 88

Pro-Oceanus Systems strives on excellence and reliability when it comes to our instruments and clients. We design an array of high precision instruments to measure dissolved gases. With highly experienced and well rounded staff, we provide, in real time, the highest accuracy and durability in the harshest of conditions. Communication is key, not only between the instrument and you, but between your team and ours.

Email: Sales@pro-oceanus.com

Web: www.pro-oceanus.com

PYRO SCIENCE

Booth 97

Pyro Science is dedicated to research tools in life sciences for analysing chemical and physical parameters at the microscale (e.g. oxygen and pH microsensors, scalar irradiance microsensors). We offer complete microprofiling setups with motorized micromanipulators and versatile control software.

Email: info@pyro-science.com

Web: www.pyro-science.com

RBR RICHARD BRANCKER RESEARCH LTD.

Co-Exhibitor on booth 82

RBR design and build rugged precision instruments for tides & waves, water quality and physical oceanography for autonomous recording or real time transmission. RBR instrumentation can incorporate sensors for conductivity, temperature, depth and many other physical, biological and chemical sensors. They feature high accuracy with low power consumption and flexible channel choices in small lightweight packages making them ideal for single handed deployment from small vessels. The range includes the small TR-1060 temperature recorder, the XRX 10-channel upgradable multi-parameter logger, a configurable central data controller, the MS-310 low cost high accuracy portable salinometer and a vented tide & wave gauge.

Email: info@rbr-global.com

Web: www.rbr-global.com

R&D-Programme GEOTECHNOLOGIEN

Booths 28, 29

GEOTECHNOLOGIEN is a national transdisciplinary R&D-Programme funded by the German Federal Ministry of Education and Research (BMBF) and the German Research Council (DFG). In joint projects between academia and industry new concepts for the protection and the sustainable use of "System Earth" will be developed. Since 2000 more than 100 joint projects have been funded, incorporating 44 universities, 31 research labs and 52 industrial partners.

Email: stroink@gfz-potsdam.de

Web: www.geotechnologien.de

REEDEREI F. LAEISZ GMBH (Bremerhaven)

Co-Exhibitor on booth 24

The F. Laeisz Shipping Group is one of the leading shipping companies in Germany with approximately 1100 crew onboard and about 150 employees ashore. F. Laeisz Shipping Group operates Bulk carriers, Reefer vessels, Gas

Exhibitor Profiles

carriers, Ro-Ro/Pax vessels and Research vessels.

The office in Bremerhaven is responsible for the management of the research vessels, amongst them the two major German research vessels RV Polarstern and RV Meteor. Also, the German Antarctic research base Neumayer (newly built in 2009, owned by the Alfred-Wegener-Institute) is managed by Reederei F. Laeisz. In addition, the four research vessels Uthörn, Aade, Diker and Mya performing mainly fishery research in the North Sea, are operated by the Bremerhaven office.

Email: research@laeisz.de

Web: www.laeisz.de

RESON

Booth 21

RESON is a market leader in underwater acoustic sensors, state-of-the-art echosounders, multibeam sonar systems, transducers, hydrophones, and PDS200 software. RESON's SeaBat® sonars and NaviSound® echosounder systems have become an industrial standard in areas such as hydrography, dredging and offshore operations as well as within defense and security applications.

Email: reson@reson-gmbh.de

Web: www.reson.com

RF FORSCHUNGSSCHIFFFAHRT GMBH

Booth 94

Since the formation of RF Forschungsschiffahrt more than 30 years ago, we have provided our customers with research vessels that feature a state-of-the-art technology. We possess highly experienced crew on board our ships as well as a skilled staff ashore; both of which have many years of experience in the special field of research vessel navigation.

The research programmes undertaken on board our vessels serve as basic research as well as application-oriented research and extend to all fields of scientific marine research as, for example, marine geosciences, oceanography, marine physics, hydrography, chemical oceanography, marine- and fishing-biology. New and further developments of equipment in the field of scientific marine research and offshore technology are regularly tested on board our vessels. Our equipment of special lifting gears and high-capacity winches offers ideal preconditions for these purposes. The RF Forschungsschiffahrt belongs to the Linnhoff shipping group since 2001 and is certified according to the ISM-code (International Safety Management Code).

Email: info@rf-bremen.de

Web: www.rf-bremen.de

SEA-BIRD ELECTRONICS, INC.

Booths 60, 61

Sea-Bird Electronics, Inc. is the leading manufacturer of oceanographic profiling CTDs and integrated water sampling systems, multi-parameter profilers, moored time-series temperature/salinity recorders, real-time inductive telemetry instruments and modems, and wave/tide and deep bottom pressure recorders. Our products enable oceanographers to determine salinity, density, and other properties contributing to ocean circulation, the function of marine ecosystems, and global climate dynamics. Sea-Bird has been serving customers in universities, oceanographic institutes, government agencies, engineering firms, and navies throughout the world for over 30 years, and has built a reputation for producing the most accurate data possible.

Email: seabird@seabird.com

Web: www.seabird.com

TELEDYNE BENTHOS

Co-Exhibitor on booths 38, 39, 40, 49, 50, 51

Teledyne Benthos is a leading provider of high technology products and integrated systems that are used for measurement, inspection, data collection and communication in remote and challenging marine environments. Products include geophysical survey systems, side scan sonar systems, glass flotation spheres, acoustic releases, hydrophones, underwater modems, pingers and other equipment for deep and shallow water applications. In Bremen, we will show a new small powerful inspection ROV.

Email: benthos@teledyne.com

Web: www.benthos.com

TELEDYNE RD INSTRUMENTS

Co-Exhibitor on booths 38, 39, 40, 49, 50, 51

With over 20 years of experience, and over ten thousand ADCP's in operation around the globe, Teledyne RDI is the leading manufacturer of precision Acoustic Doppler Current Profilers and waves measurement products for estuary, coastal and offshore applications. In Bremen we will show the new Doppler Volume Sampler DVS which can provide substantially improved data quality over traditional single point solutions, allowing 5 bins of high resolution velocity data over a range of up to 5m.

Email: rdisales@teledyne.com

Web: www.rdinstruments.com

TITANIUM SOLUTIONS GMBH

Co-Exhibitor on booth 41

Titanium Solutions GmbH offers tailor-made solutions for our customers: forged parts, cast parts or totally processed components up to fully operating robots. With this company we process and improve products for following applications: Automotive, Medicine, Offshore and we are in constant dialogue with Universities and Research-Institutes in order to link our Know How with latest findings of research.

Email: HWH-Bremen@tibar.de

Web: www.tibar.de

TRIOS OPTICAL SENSOR

Co-Exhibitor on booths 113, 114, 115

TriOS Optical Sensors is offering newest technology in optical sensors. Our strengths are high precision and clean measurement principles for highly customized and operational solutions for light measurements, chemical free substance analysis and water monitoring. Founded as a spin-off company of the University of Oldenburg in 1998, TriOS and its research partners from world leading institutes and universities stand for innovations in optical sensors.

Email: info@trios.de

Web: www.trios.de

TRITECH INTERNATIONAL LIMITED

Booth 43

Tritech International Ltd started trading in 1990 with the aim of producing the finest, most innovative range of subsea products available. The award winning company specialises in the production of high performance acoustic sensors, video cameras and mechanical tooling equipment for professional underwater markets. As an innovator in the marketplace Trittech remains industry leader in the provision of sensors and tools for ROV and AUV markets.

Tritech is based in Westhill, Aberdeenshire, with its design and manufacturing base located in Ulverston, Cumbria. In 2006 Trittech became part of Halma p.l.c. which also acquired SRD (Sonar Research & Development) in 2007. SRD specialises in multi-beam sonar technology, based in Beverley, East Yorkshire and is now part of the Trittech Group.

Email: sales@tritech.co.uk

Web: www.tritech.co.uk

VALEPORT LTD.

Co-Exhibitor on booths 62, 63

Now in their 40th year, Valeport continue as the UK's leading manufacturer

Exhibitor Profiles

of Oceanographic and Hydrographic instrumentation which include Current Meters, Tide Gauges, Wave Recorders, CTD's, Multi-Parameter CTD's, high accuracy Sound Velocity Probes / Sensors, GPS Echo Sounders, Loggers and Customised Packages. Engineered solutions to your monitoring challenge.

Email: sales@valeport.co.uk

Web: www.valeport.co.uk

WERUM SOFTWARE & SYSTEMS AG

Booth 35

Werum Software & Systems offers a wide range of maritime applications for use in ocean research. Werum's platform in this sector is DAVIS-SHIP, a test data management system specially developed for research vessels. DAVIS-SHIP operates successfully on large and medium-sized German and international research vessels, where it manages scientific data captured by onboard equipment instrumentation or remotely operated vehicles (ROV). Werum's PERPLEX® software is a computer-aided system used for dynamic planning and execution of marine scientific expeditions. Last but not least, Werum has accumulated wide-ranging expertise in marine environmental monitoring networks. The IT company was founded in 1969 and is headquartered in Lueneburg, Germany. It currently employs more than 335 people in Germany, the USA, Japan, and Singapore.

Email: info@werum.de

Web: www.werum.de

WET LABS, INC.

Co-Exhibitor on booths 38, 39, 40, 49, 50, 51

At Wet Labs we are dedicated to developing and manufacturing underwater instrumentation to detect vital biological, chemical and geological parameters and processes of the earth's oceans, lakes and streams. Our leading edge instruments include fluorometers, transmissimeters, scattering sensors, and spectrophotometers that reliably provide accurate data about the Inherent Optical Properties of the aquatic environment. In Bremen we will show the new Water Quality Monitor WQM, an instrument which will provide temperature, dissolved oxygen, chlorophyll, fluorescence, turbidity and salinity data with all sensors protected from bio fouling.

Email: sales@wetlabs.com

Web: www.wetlabs.com

WIND ENERGY AGENCY BREMERHAVEN/BREMEN E.V. (WAB)

Co-Exhibitor on booths 113, 114, 115

The Wind Energy Agency Bremerhaven/Bremen e.V. (WAB) is the industry network for wind energy in northwest Germany. More than 190 companies and institutes are members of WAB and represent all sectors of the wind industry. The goal of WAB is to support the regional sector in further developing wind power!

Email: info@windenergie-agentur.de

Web: www.windenergie-agentur.de

WIRELESS FIBRE SYSTEMS LTD

Booth 8

WFS is the world's leading developer of through-water and through-ground electromagnetic communications and sensing products. With over 50 patent applications filed in Europe and North America, our revolutionary products deliver cost savings and new capabilities to the Oil & Gas, Environmental & Industrial, and Homeland Security & Defence industries. WFS launched the world's first commercially available underwater Radio Modem, Seatext®, in 2006. WFS's Broadband Data Link, Seatooth®, was launched in January 2007 and was followed later that year by a launch of the world's first dual technology Radio Acoustic Modem, RAM-300.

Email: ian@wirelessfibre.co.uk

Web: www.wirelessfibre.co.uk

4H- JENA ENGINEERING GMBH

Booth 36

4H- JENA engineering GmbH is active in research and development of innovative and stable measuring systems cooperation with numerous national and international institutes and universities.

The product line of the marine technology division comprises single and multi parameter probe, measuring containers, measuring buoys, offshore platforms, measuring piles, flow-through-systems with integrated anti-fouling-units for rivers and coastal water.

Email: boehme@4h-jena.de

Web: www.4h-jena.de

Exhibit Floor Plan

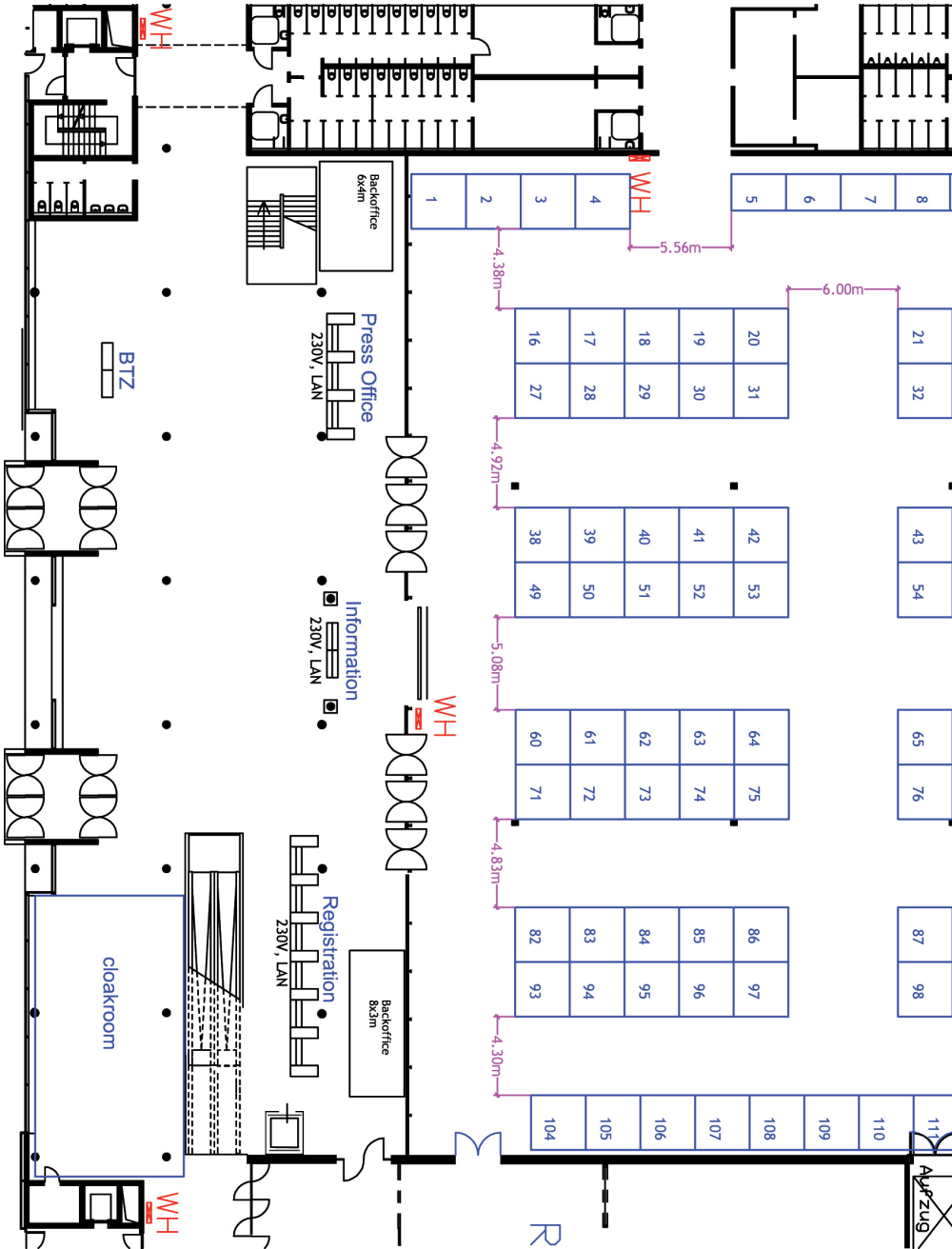
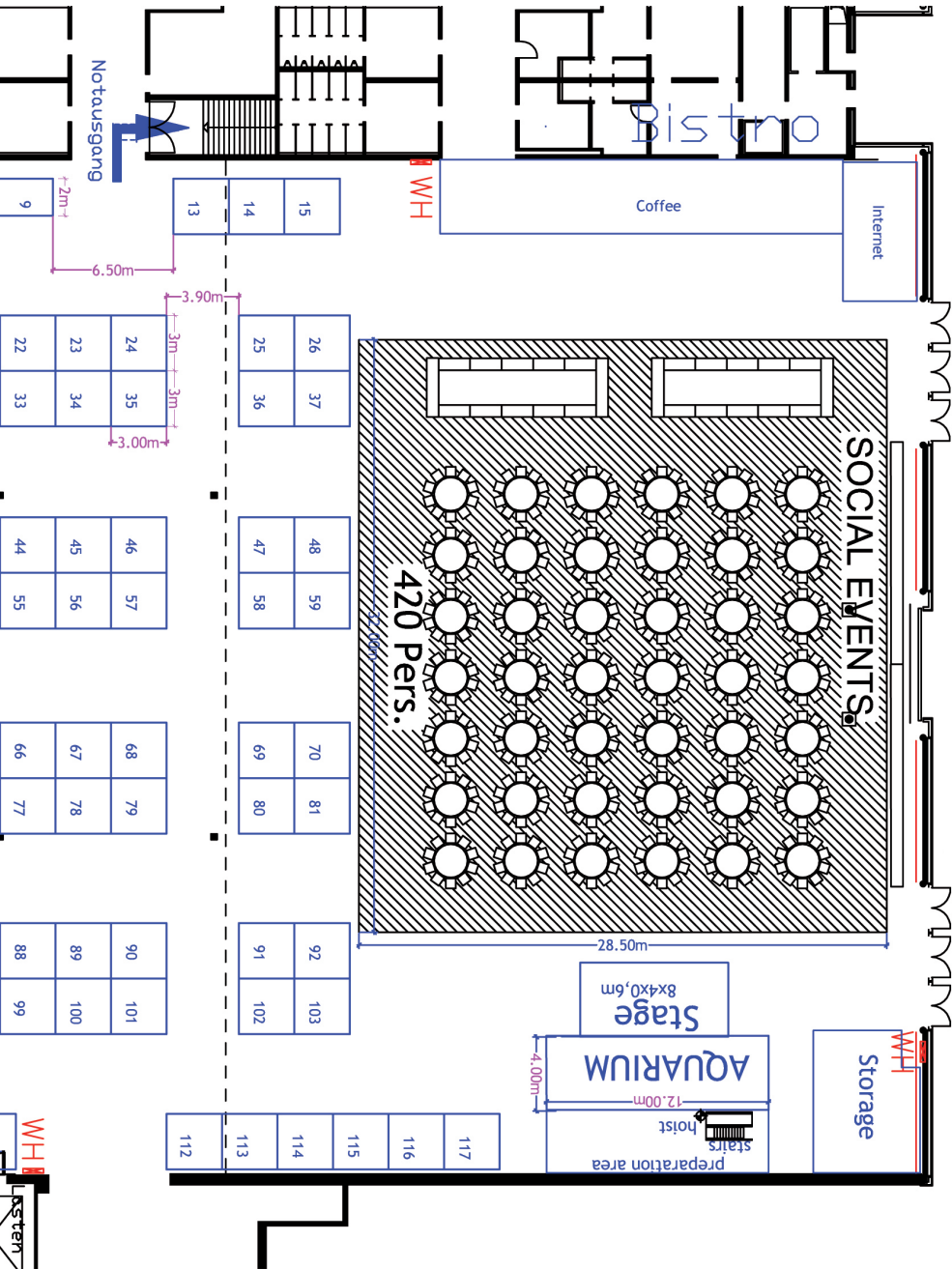


Exhibit Floor Plan



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Briese Schiffahrts GmbH & Co. KG
Abteilung Forschungsschifffahrt



MariPro



ELAC Nautik



A joint company of ThyssenKrupp and EADS

SUPPORTING PARTNERS:



KONGSBERG



MEDIA PARTNERS:



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